

# electromagnetic geophysics across the scales

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# some important problems



minerals



contaminants



water



geothermal



geotechnical



slope stability



hydrocarbons



unexploded ordnance

have in common: electrical conductivity can be a diagnostic physical property

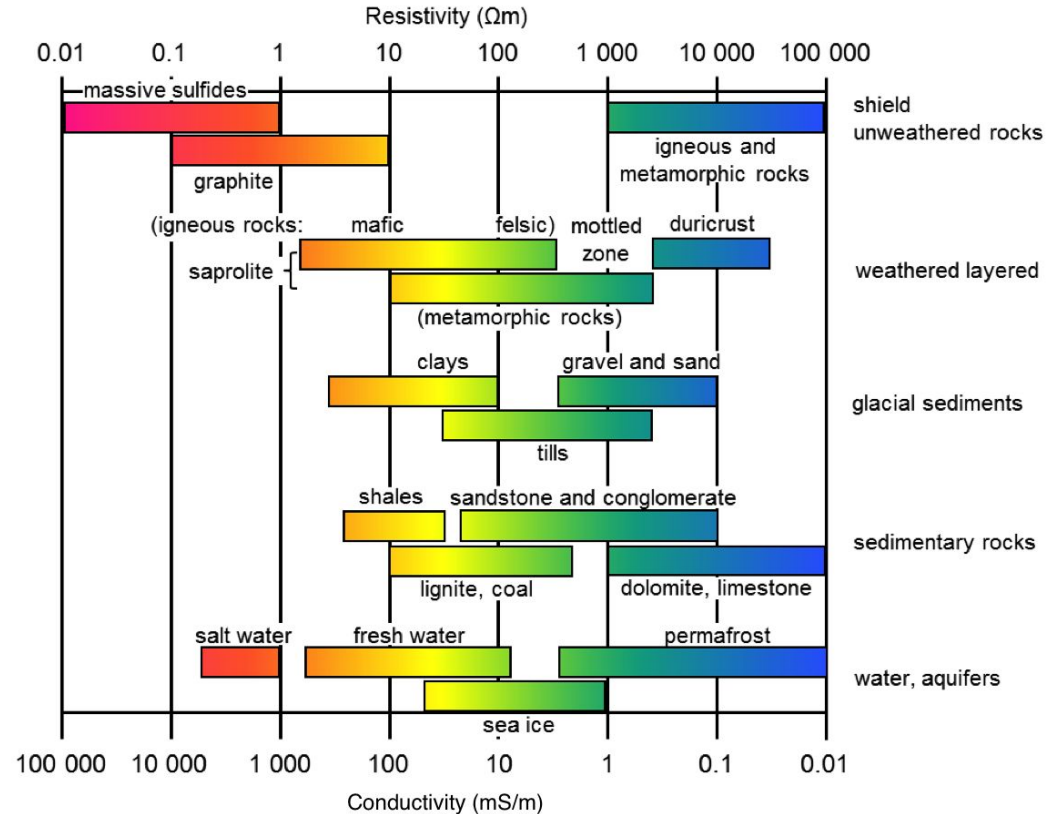
# electrical conductivity / resistivity

A measure of how easily current passes through a material

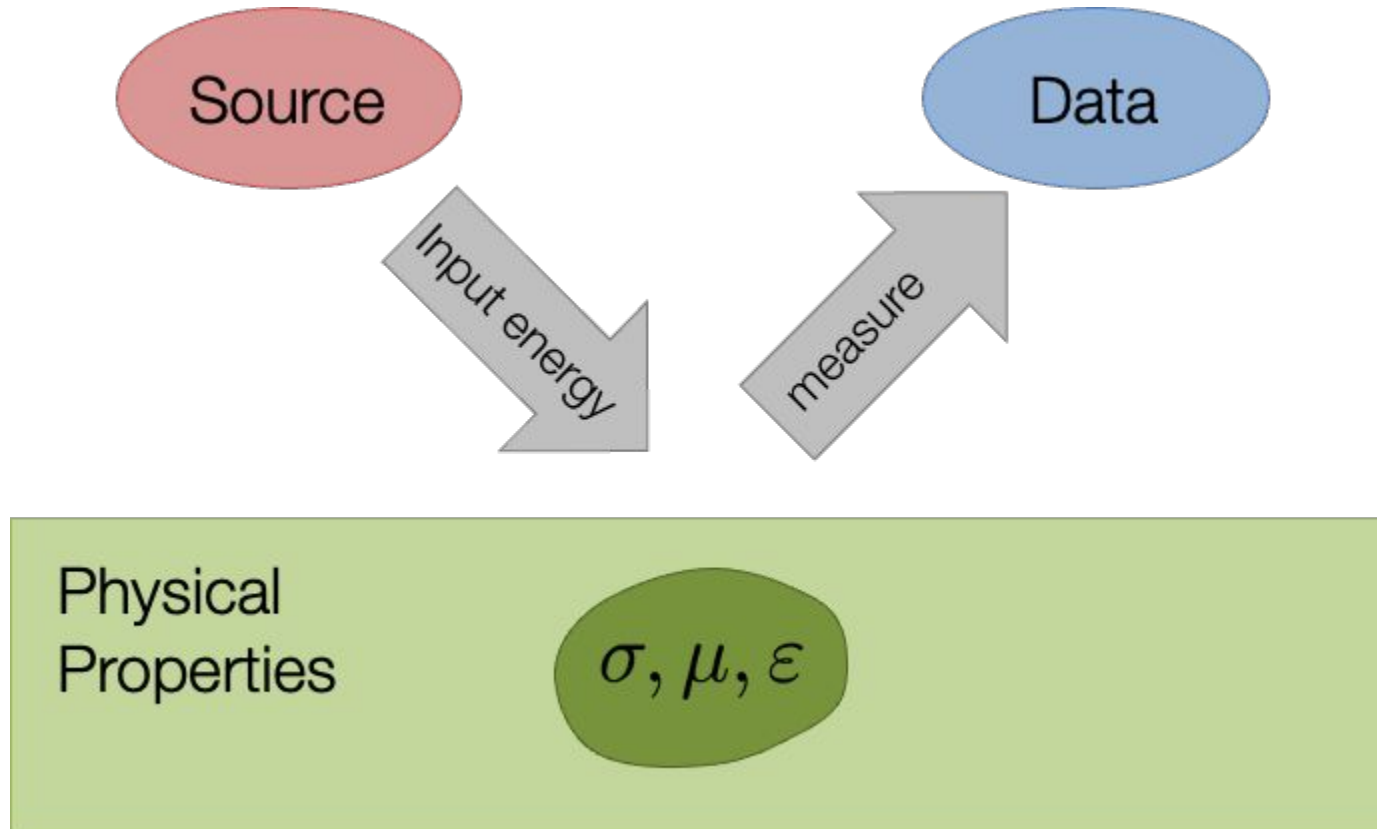
- $\sigma$ : conductivity [S/m]
- $\rho$ : resistivity [ $\Omega\text{m}$ ]
- $\rho = 1/\sigma$

Depends on many factors

- Mineralogy
- Porosity
- Permeability
- Nature of pore fluid



# geophysical experiments & physical properties



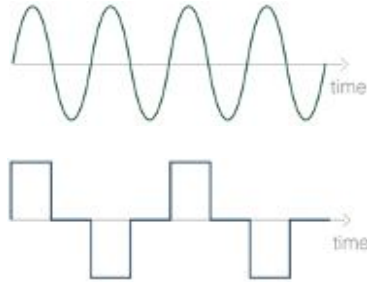
# electromagnetic experiments

## Sources:

- grounded or inductive
- controlled or natural

## Waveform

- harmonic (FDEM)
- transient (TDEM)

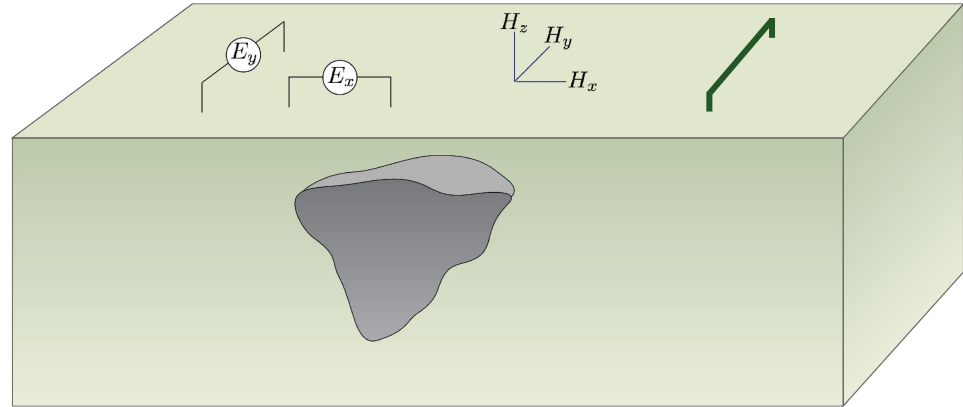
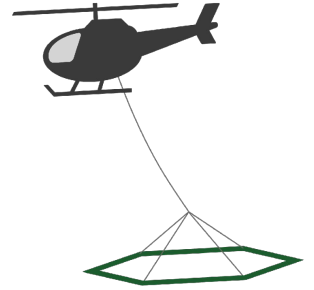


## Survey location

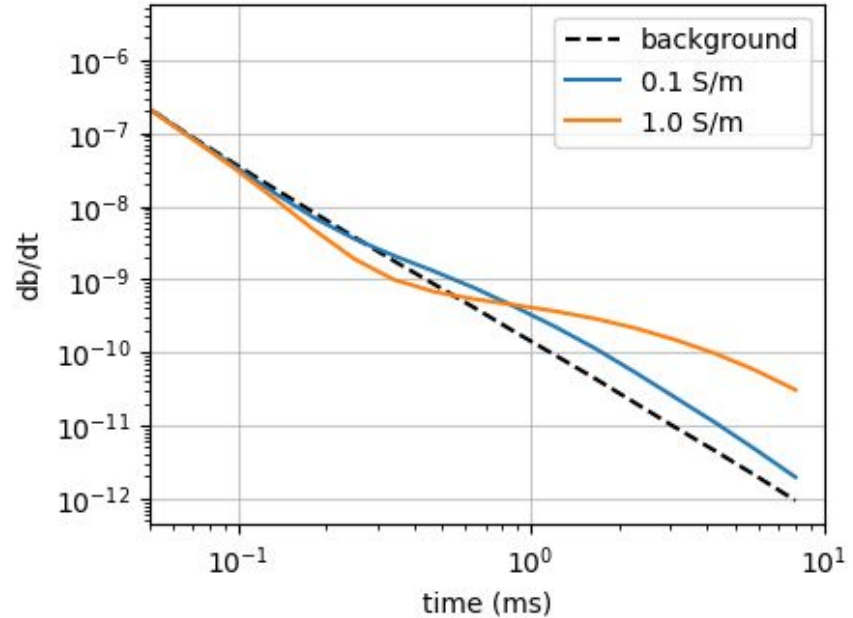
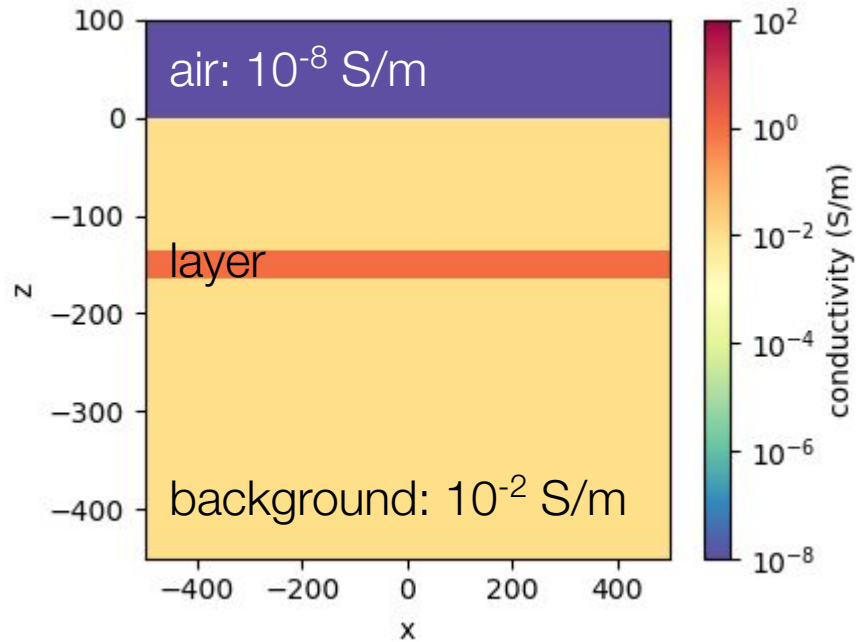
- airborne
- ground
- boreholes

$$\nabla \times \vec{e} = -\frac{\partial \vec{b}}{\partial t}$$

$$\nabla \times \vec{h} = \vec{j} + \frac{\partial \vec{d}}{\partial t}$$



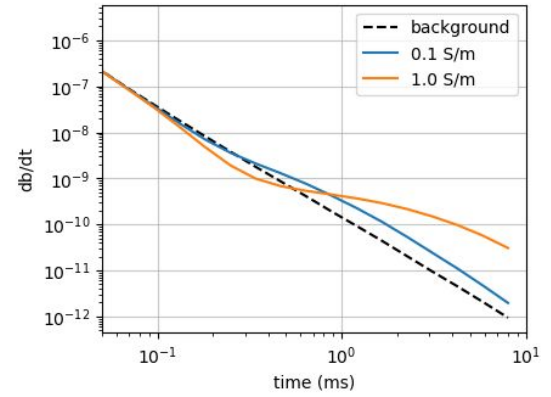
# physics: time-domain



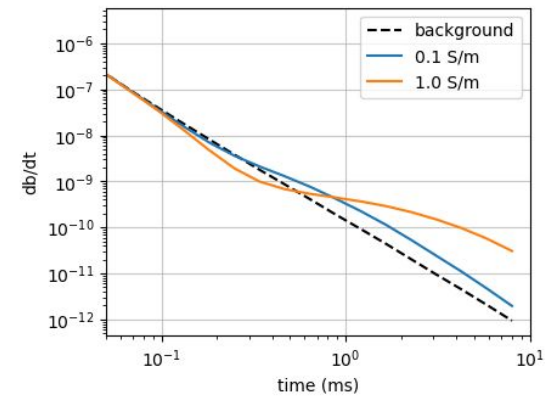
physics: time-domain

current density

db/dt

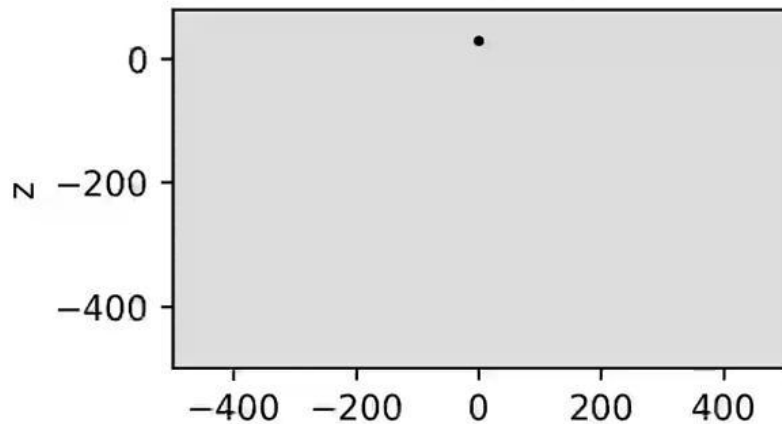


# physics: time-domain

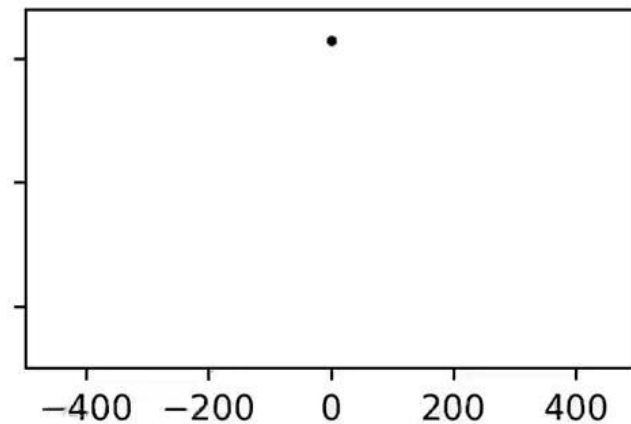


current density

$t=0.00$  ms



$db/dt$





# physics: frequency domain

high frequency ~ early times,

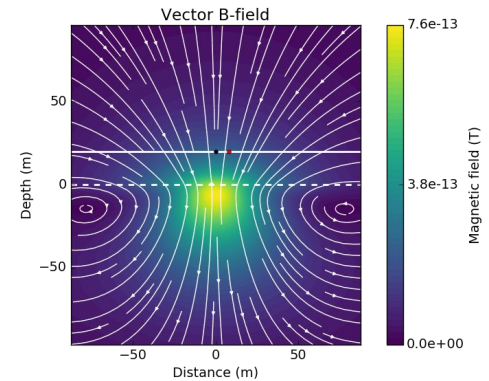
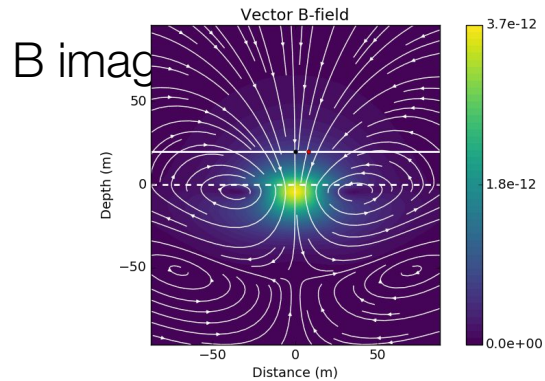
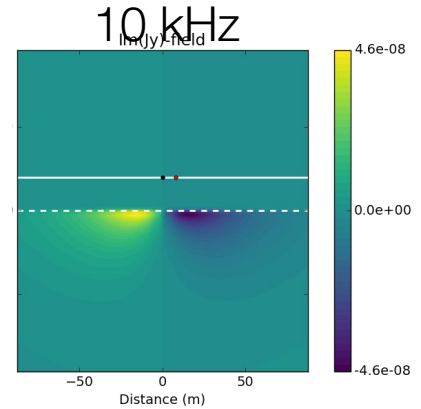
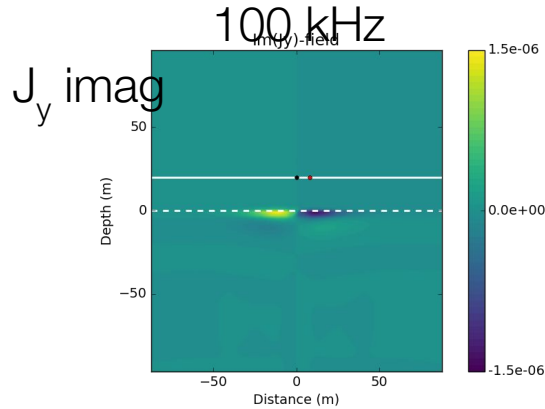
low frequency ~ later times

skin depth

$$\delta = 503 \sqrt{\frac{\rho}{f}}$$

$\rho$ : resistivity [ $\Omega\text{m}$ ]

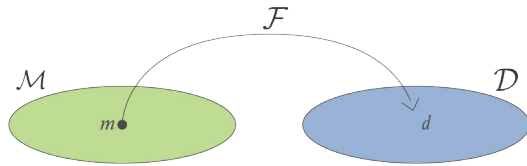
$f$ : frequency [Hz]



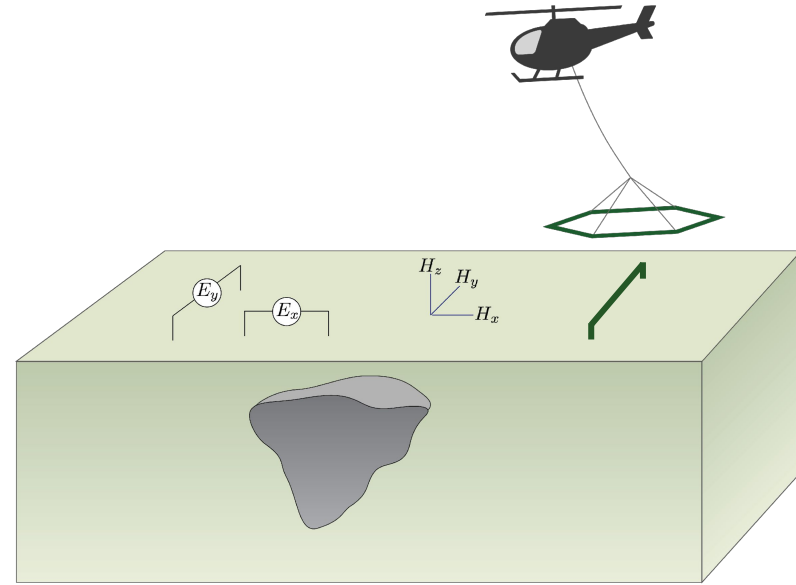
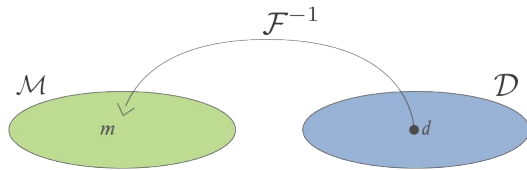
# statement of the inverse problem

Given

- observations:  $d_j^{obs}$ ,  $j = 1, \dots, N$
- uncertainties:  $\epsilon_j$
- ability to forward model:  $\mathcal{F}[m] = d$



Find the Earth model that gave rise to the data



# statement of the inverse problem

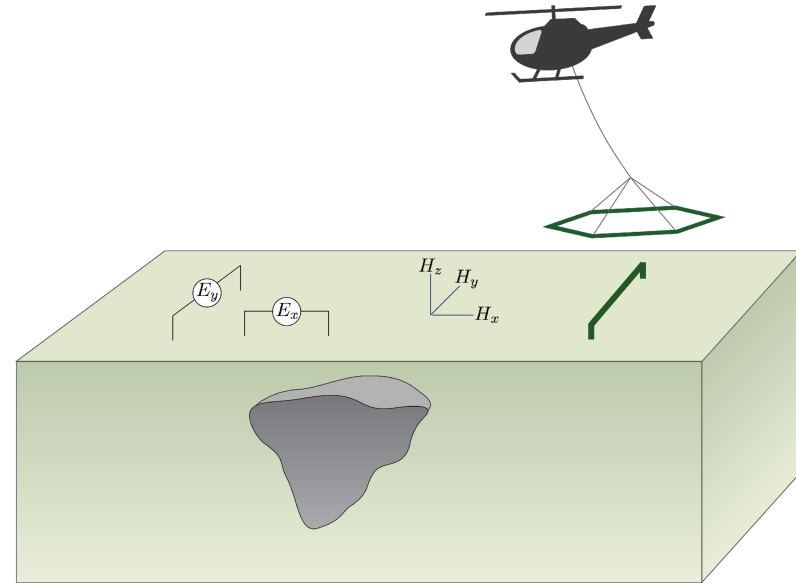
Given

- observations:  $d_j^{obs}$ ,  $j = 1, \dots, N$
- uncertainties:  $\epsilon_j$
- ability to forward model:  $\mathcal{F}[m] = d$

Inverse problem: Find an Earth model that fits those data and a-priori information

$$\min_{\mathbf{m}} \phi(\mathbf{m}) = \phi_d(\mathbf{m}) + \beta\phi_m(\mathbf{m})$$

$$\text{s.t. } \phi_d \leq \phi_d^* \quad \mathbf{m}_L \leq \mathbf{m} \leq \mathbf{m}_U$$





*Simulation and parameter estimation in geophysics*

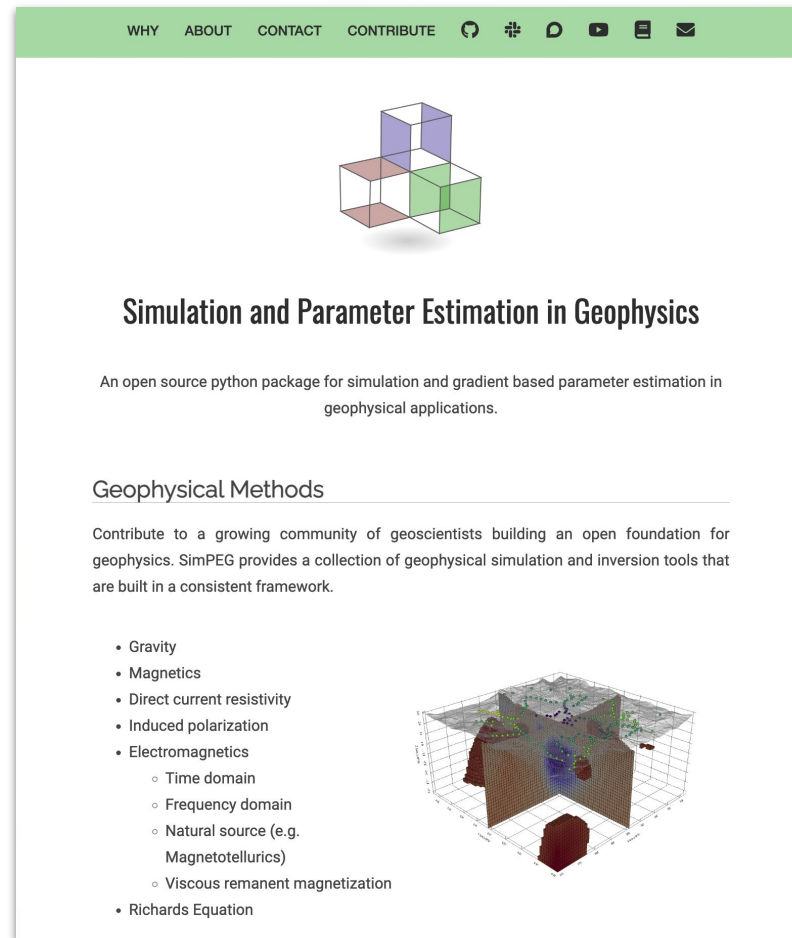
common framework for simulations & inversions

accelerate research: build upon others work

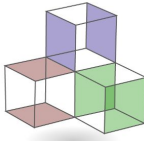
facilitate reproducibility of results

build & deploy in python

open-source

A screenshot of the SimPEG website. The top navigation bar is green and contains links for WHY, ABOUT, CONTACT, and CONTRIBUTE, along with social media icons for GitHub, YouTube, and Twitter. The main content area features the SimPEG logo, a title "Simulation and Parameter Estimation in Geophysics", a subtitle "An open source python package for simulation and gradient based parameter estimation in geophysical applications.", a section for "Geophysical Methods" with a list of methods, and a 3D visualization of a subsurface model with various colored regions representing different geological or physical properties.

WHY ABOUT CONTACT CONTRIBUTE



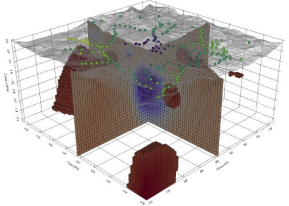
## Simulation and Parameter Estimation in Geophysics

An open source python package for simulation and gradient based parameter estimation in geophysical applications.

### Geophysical Methods

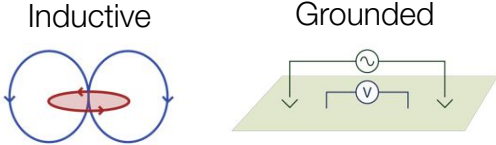
Contribute to a growing community of geoscientists building an open foundation for geophysics. SimPEG provides a collection of geophysical simulation and inversion tools that are built in a consistent framework.

- Gravity
- Magnetics
- Direct current resistivity
- Induced polarization
- Electromagnetics
  - Time domain
  - Frequency domain
  - Natural source (e.g. Magnetotellurics)
  - Viscous remanent magnetization
- Richards Equation



# Multi-scale EM geophysical methods

Controlled-source EM



Natural source EM



Depth from the surface



meters

Tens of meters

Hundreds of meters

Kilometers

Tens of kilometers

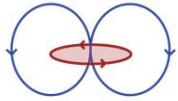
Hundreds of kilometers

# Multi-scale EM geophysical methods

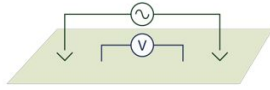
Controlled-source EM

Natural source EM

Inductive



Grounded



Depth from the surface



meters

Tens of  
meters

Hundreds  
of meters

Kilometers

Tens of  
kilometers

Hundreds of  
kilometers

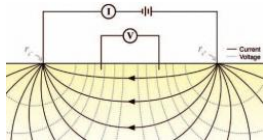
Ground-based EM

Airborne EM (AEM)

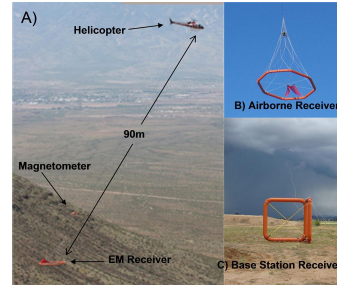
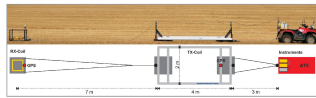
Z-axis Tipper EM (ZTEM)

Magnetotellurics (MT)

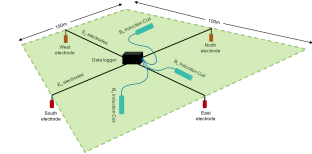
ERT



Towed-TEM



14



# important problems: scales and surveys



minerals



contaminants



water



geothermal



geotechnical



slope stability



hydrocarbons

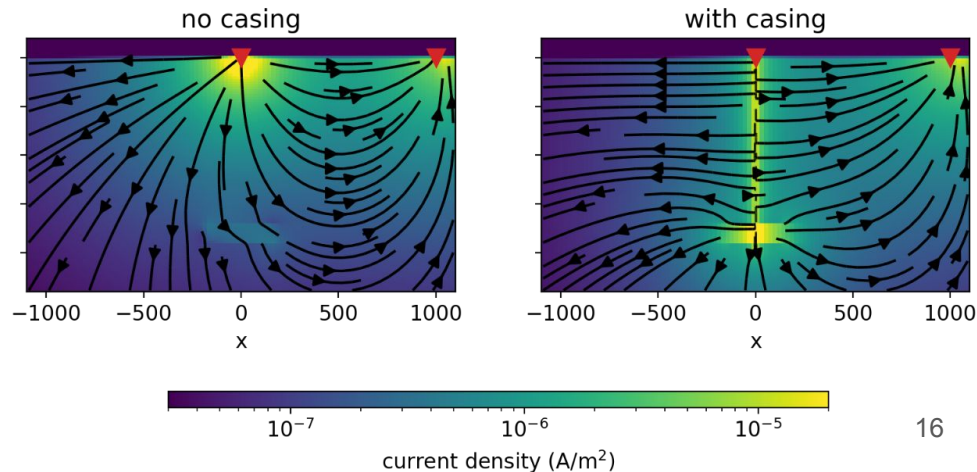
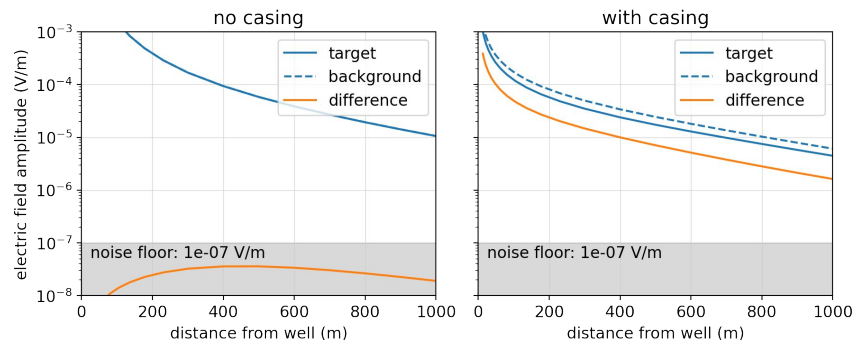
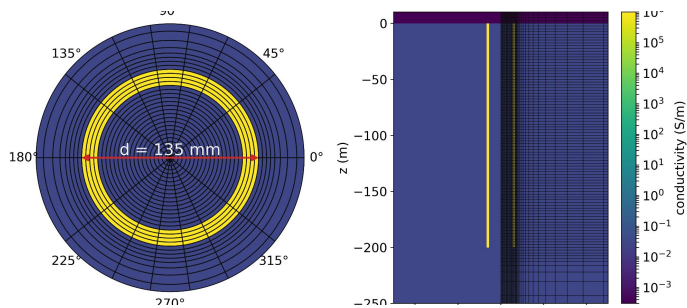
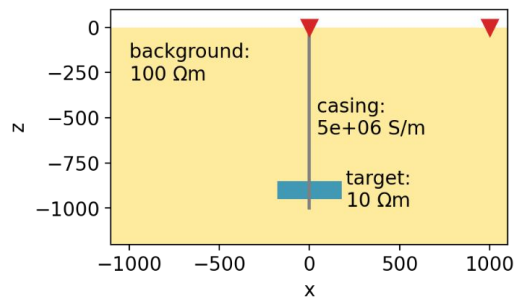


unexploded ordnance

# CO<sub>2</sub> sequestration, hydrocarbons: fine scales & large contrasts

steel casings: highly conductive, magnetic

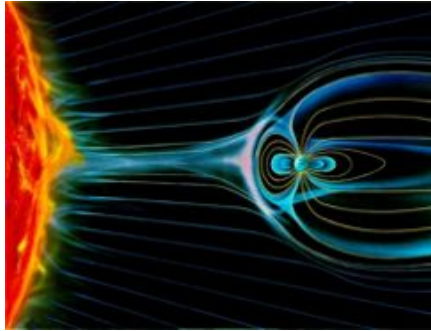
grounded sources: helpful for exciting & detecting deep targets



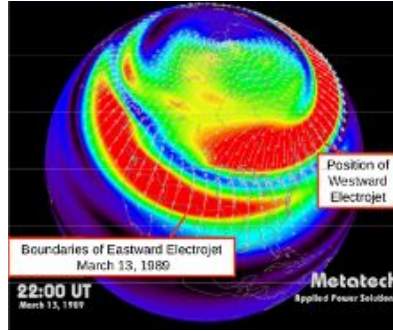


# minerals, geothermal: large scales & seeing deep

natural source: rely on lightning strikes, solar wind as our source (unknown strength)



lightning



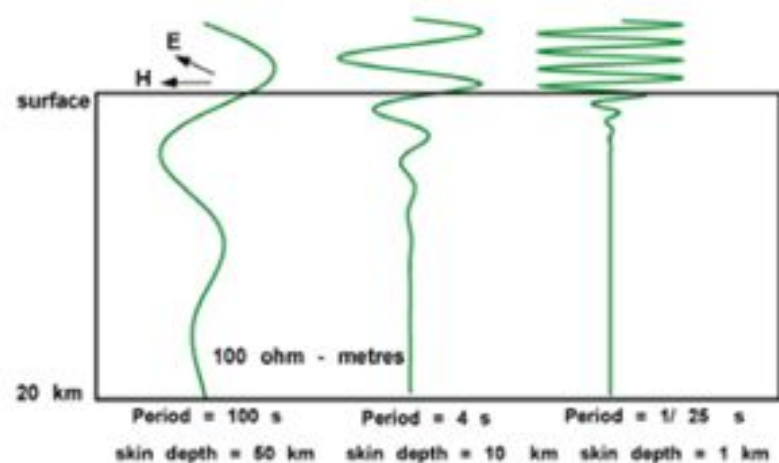
aurora



skin depth (m)

$$\delta = 503 \sqrt{\frac{\rho}{f}}$$

$\rho$  : resistivity [ $\Omega\text{m}$ ]  
 $f$  : frequency [Hz]



# unexploded ordnance: small scales

near surface (or seafloor), need to detect & classify UXO vs clutter



?

This rocket warhead was found in September, 2008.  
DEPARTMENT OF NATIONAL DEFENCE



A sign at the Goose Lake Range, on Okanagan Indian Band territory, warns of the presence of UXO. JEFF BASSETT/THE GLOBE AND MAIL

UXO



Mortar



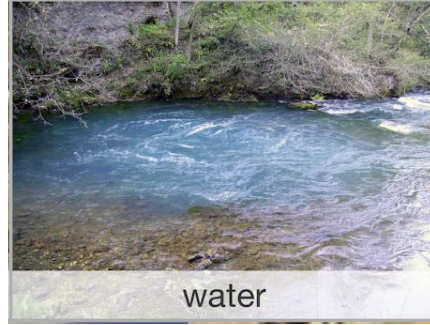
76 mm

Not UXO



popcan

# case studies



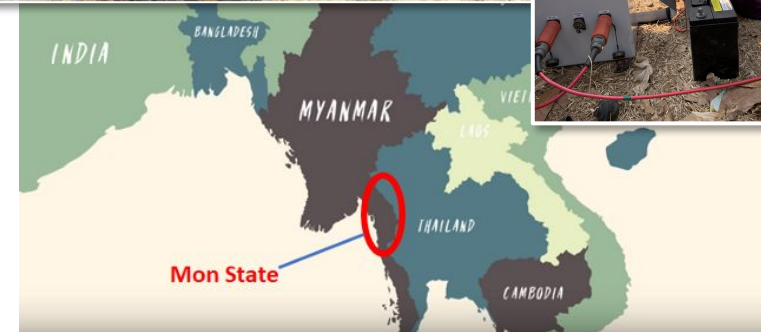
# case studies



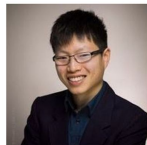
# groundwater in Myanmar

Improving Water Security in Mon state,  
Myanmar via Geophysical Capacity Building

- Bring geophysical equipment to Mon state Myanmar
- Train local stakeholders
- Provide open-source software & educational resources



Doug Oldenburg



Kevin Fan



Michael (Max)



Devin Cowan



Seogi Kang



Lindsey Heagy



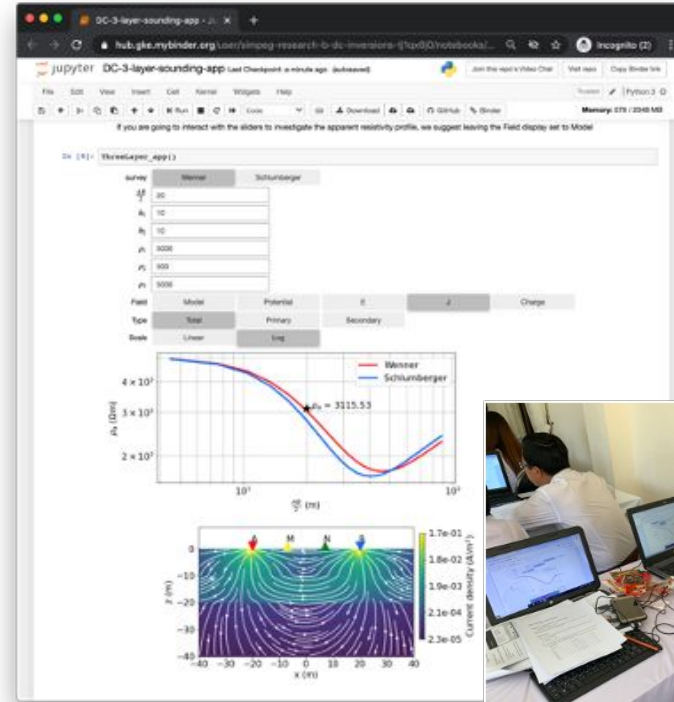
# groundwater in Myanmar: important components

## 7 step framework for case studies

- Setup
- Physical properties
- Survey
- Data
- Processing
- Interpretation
- Synthesis

## Open source software and resources

- Jupyter notebook “apps” for concepts and data processing



# groundwater in Myanmar

## 7 step framework

- **Setup**
- Physical properties
- Survey
- Data
- Processing
- Interpretation
- Synthesis

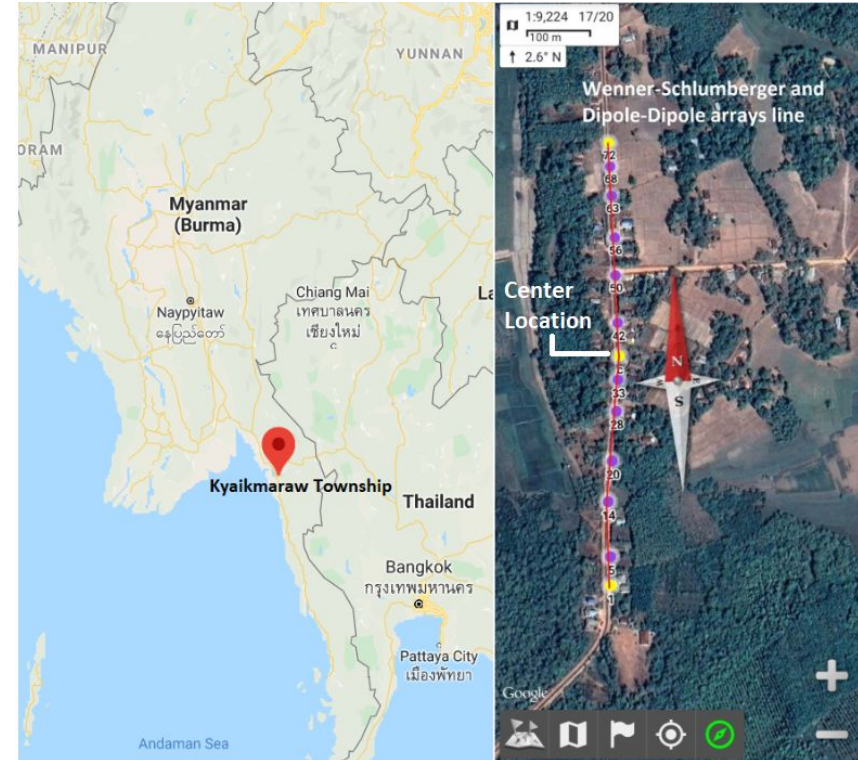
### Phayar Ngoteto Village

In 2018: 1D inversion suggested aquifer at 30-50 m

- Well drilled to ~60 m: no significant water

In 2020 (before covid...):

- return and conduct a 2D survey

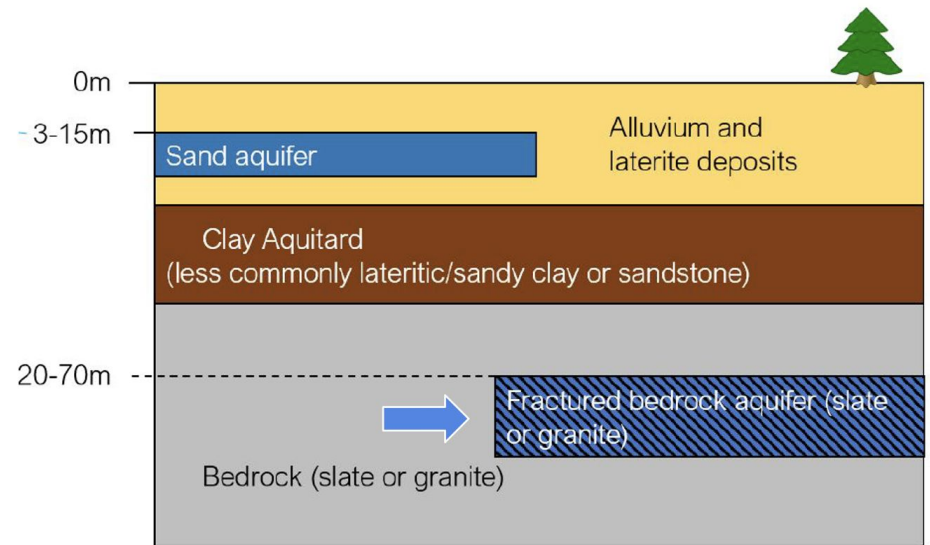


# groundwater in Myanmar

## 7 step framework

- Setup
- **Physical properties**
- Survey
- Data
- Processing
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Main diagnostic:  
Water bearing region ~ 40-140  $\Omega\text{m}$



Hydrogeological Unit	Resistivity ( $\Omega\text{m}$ )
Alluvium and laterite (dry)	200-800
Alluvium and laterite (saturated)	30
Sand aquifer	50-100
Clay aquitard	10-20
Bedrock (eg. granite)	500-1000
Fractured/Weathered bedrock (with fresh water)	40-400

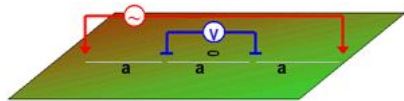


# groundwater in Myanmar

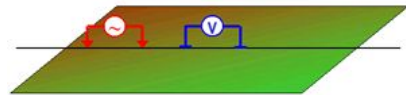
## 7 step framework

- Setup
- Physical properties
- **Survey**
- Data
- Processing
- Interpretation
- Synthesis

## Survey: 2D DC resistivity



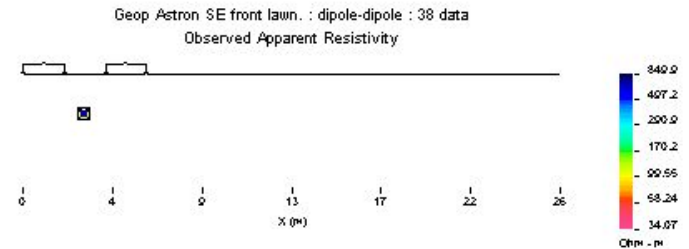
Wenner-Schlumberger



Dipole-Dipole



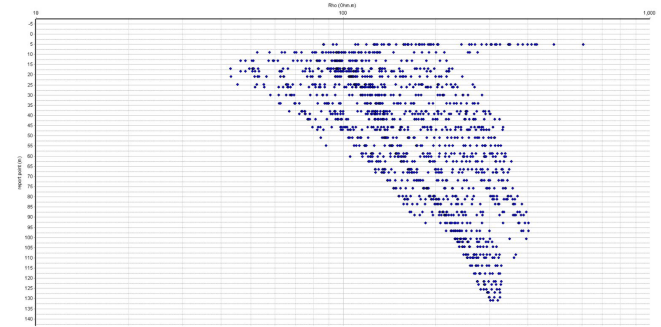
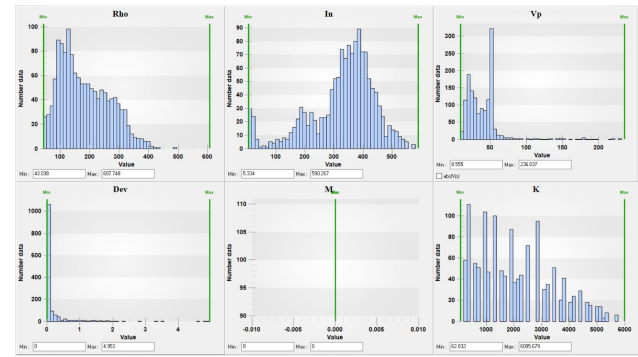
## data plotted in pseudosections



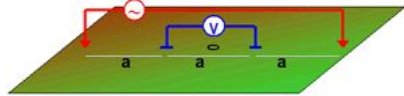
# groundwater in Myanmar

## 7 step framework

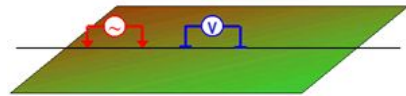
- Setup
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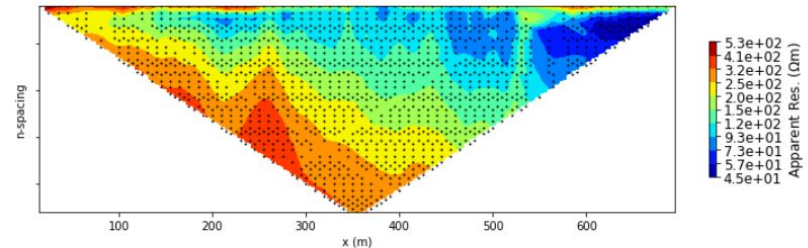
## Survey: 2D DC resistivity



Wenner-Schlumberger



Dipole-Dipole



# groundwater in Myanmar

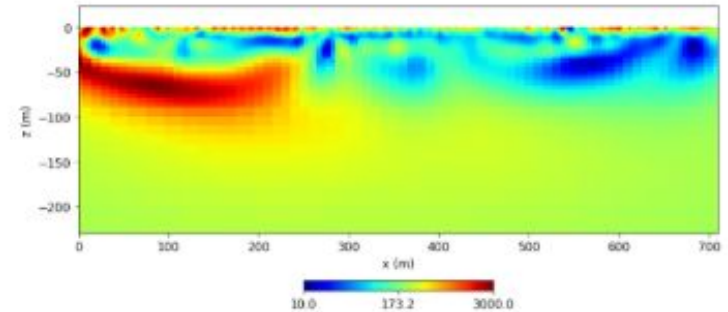
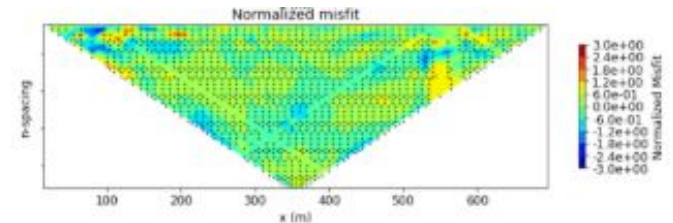
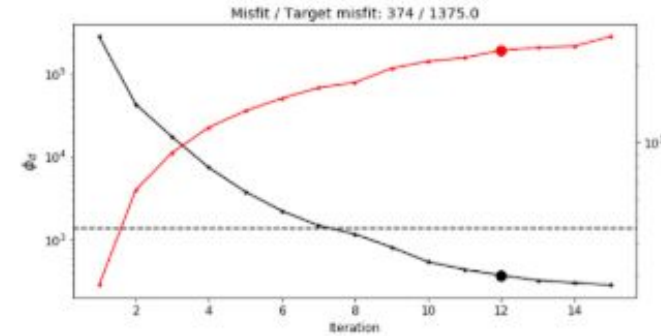
## 7 step framework

- Setup
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- Data
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Inversion: estimate a model of the subsurface

$$\min_{\mathbf{m}} \phi(\mathbf{m}) = \phi_d(\mathbf{m}) + \beta\phi_m(\mathbf{m})$$

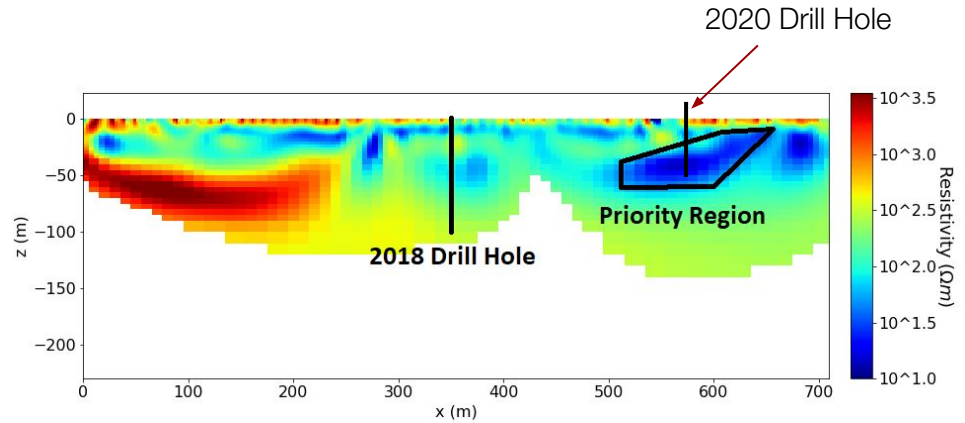
$$\text{s.t. } \phi_d \leq \phi_d^* \quad \mathbf{m}_L \leq \mathbf{m} \leq \mathbf{m}_U$$



# groundwater in Myanmar

## 7 step framework

- Setup
- Physical properties
- Survey
- Data
- Processing
- **Interpretation**
- Synthesis



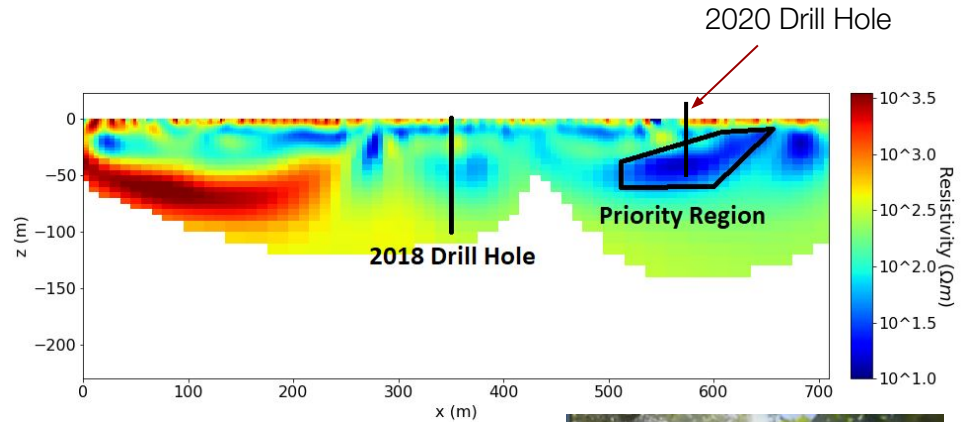
# groundwater in Myanmar

## 7 step framework

- Setup
- Physical properties
- Survey
- Data
- Processing
- Interpretation
- **Synthesis**

Field surveys at 23+ villages by engineers, geoscientists in Myanmar

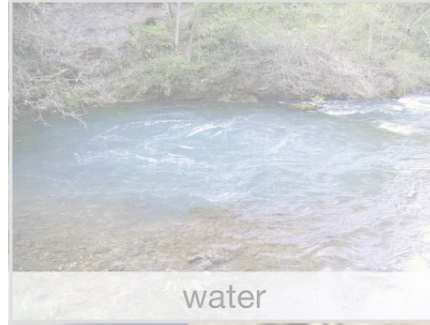
Acquired data, interpreted, spotted drill holes using open source software



>1000 gph



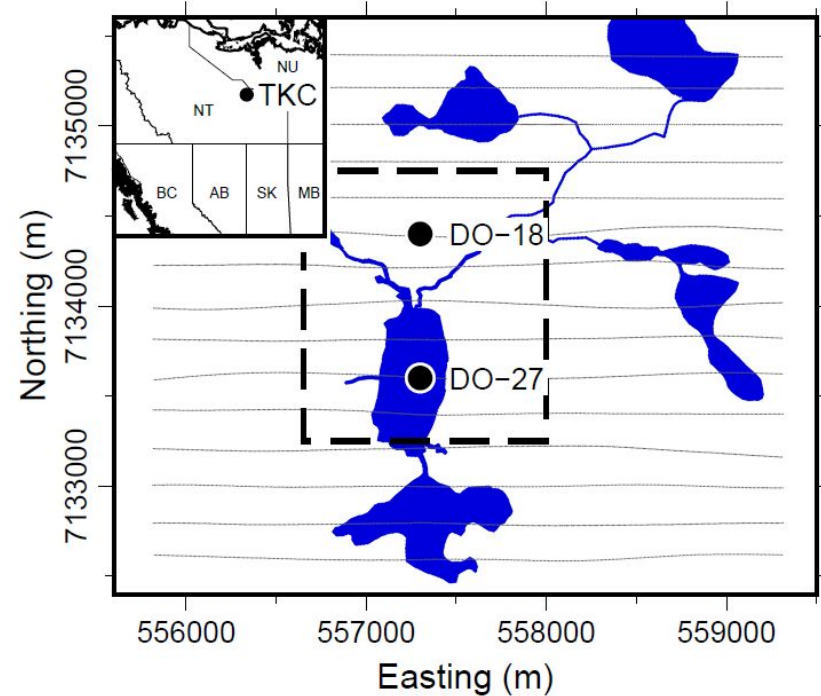
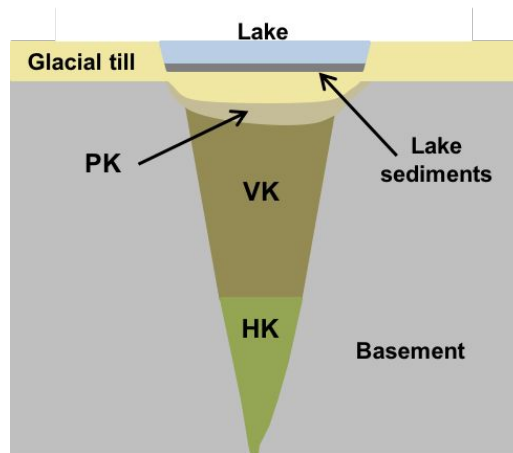
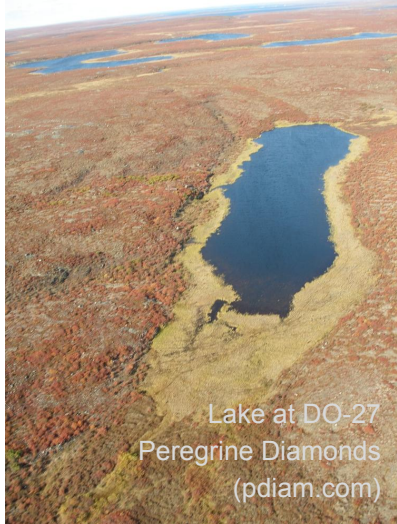
# case studies



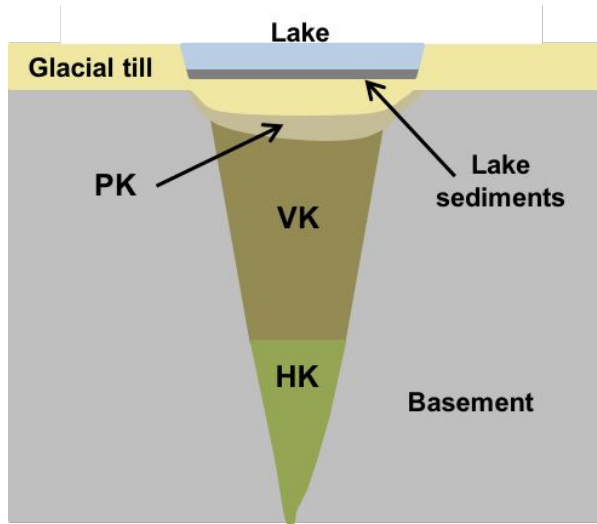
# Tli Kwi Cho (TKC) Kimberlite complex

Geophysical discovery in 90's: airborne magnetic and electromagnetic data

2 kimberlite pipes



# physical properties at TKC



Rock type	Glacial till	Host rock	HK	VK	PK
Density	Moderate	Moderate	Low	Low	Low
Susceptibility	None	None	High	Low-moderate	Low-moderate
Conductivity	Moderate-high	Low	Low-moderate	Moderate-high	Moderate-high
Chargeability	Low	Low	?	?	?

- Overall kimberlite: low density
- HK: high susceptibility
- VK and PK:
  - low-moderate susceptibility
  - moderate-high conductivity

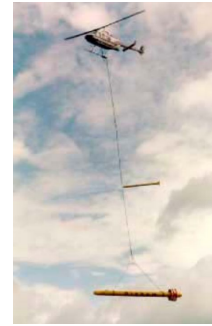


# TKC: surveys

Airborne data

System	Year	Data
DIGHEM	1992	FEM, mag
Falcon	2001	Grav grad
AeroTEM II	2003	TEM, mag
VTEM	2004	TEM, mag

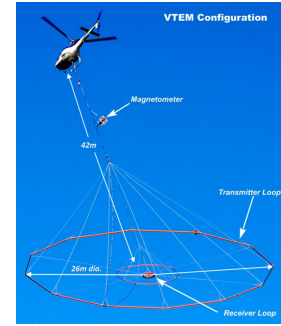
Ground data as well: NanoTEM,  
magnetics, gravity



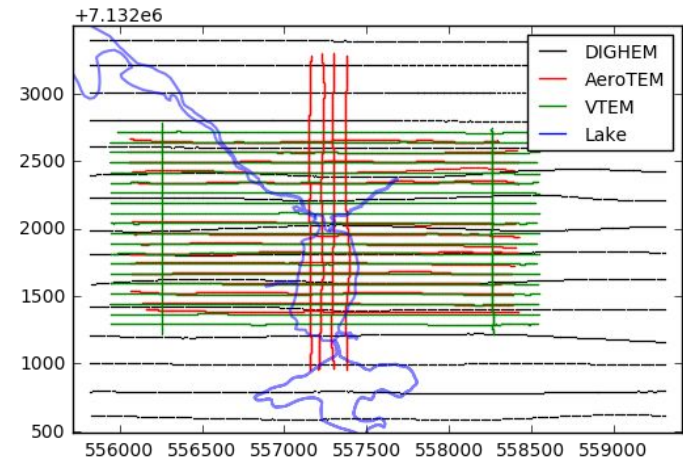
DIGHEM



AeroTEM



VTEM



# TKC: data

## Airborne data

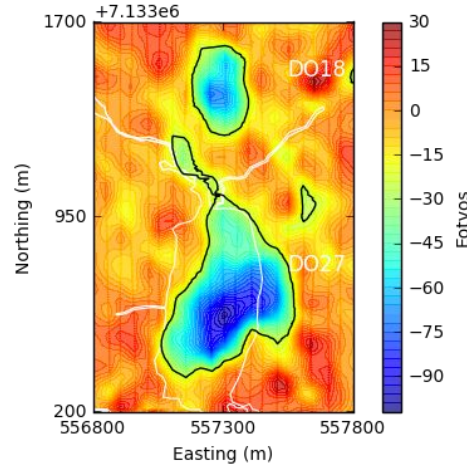
- invert to obtain physical property models
- interpret to build quasi-geology model
- published in 3 papers by the GIF group

*Devriese et al. 2017,*

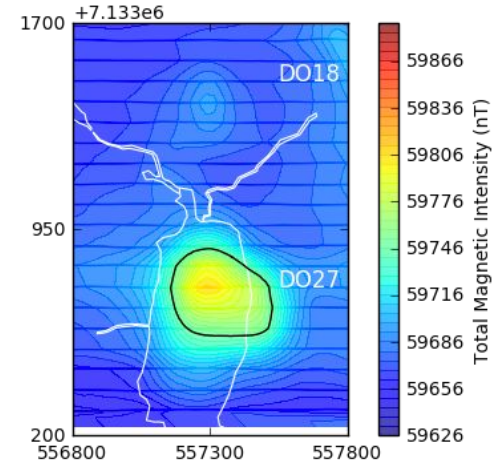
*Fournier et al. 2017,*

*Kang et al. 2017*

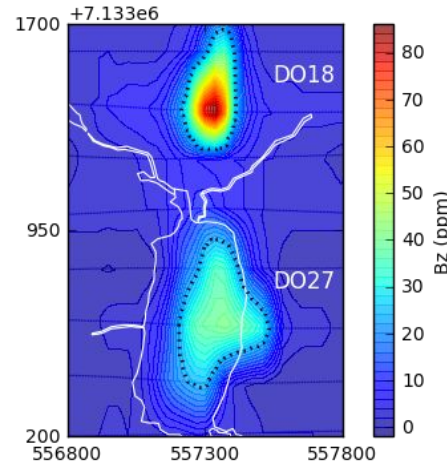
gravity gradiometry



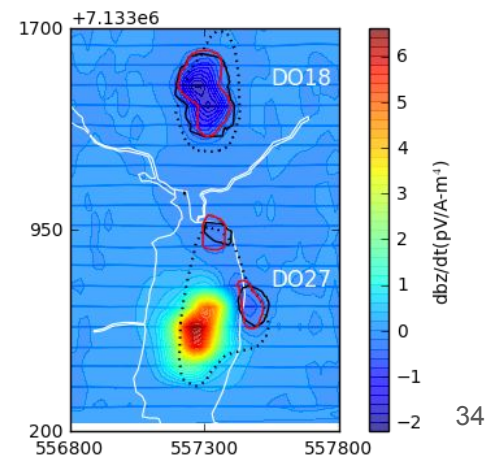
VTEM mag



frequency domain EM



VTEM

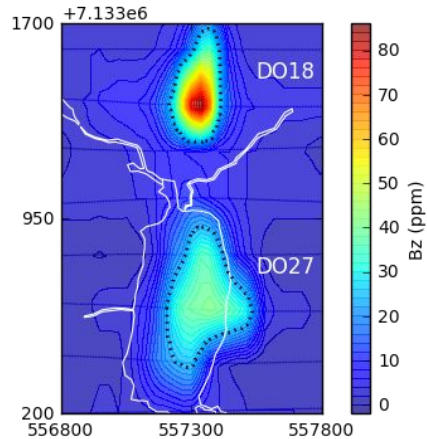


# TKC: electromagnetics

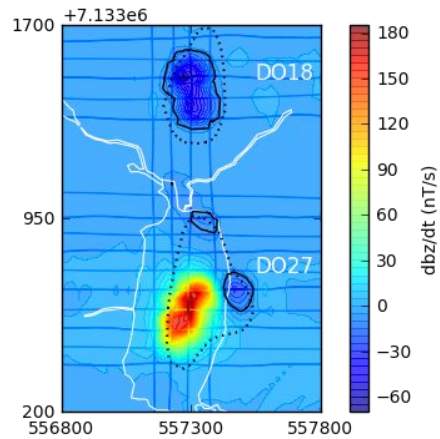
Focus on DIGHEM and VTEM data

Negatives in VTEM data is challenge...

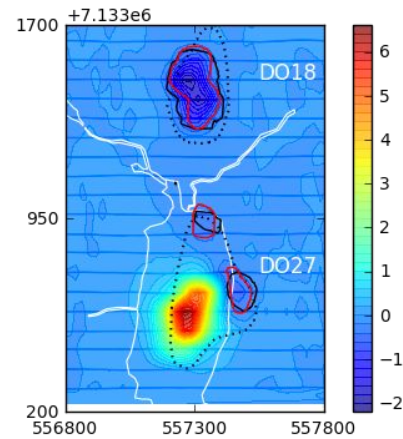
DIGHEM  
(1992)



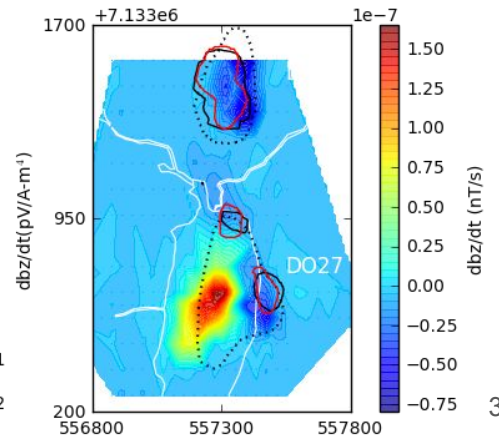
AeroTEMI  
(2003)



VTEM  
(2004)



NanoTEM  
(1993)



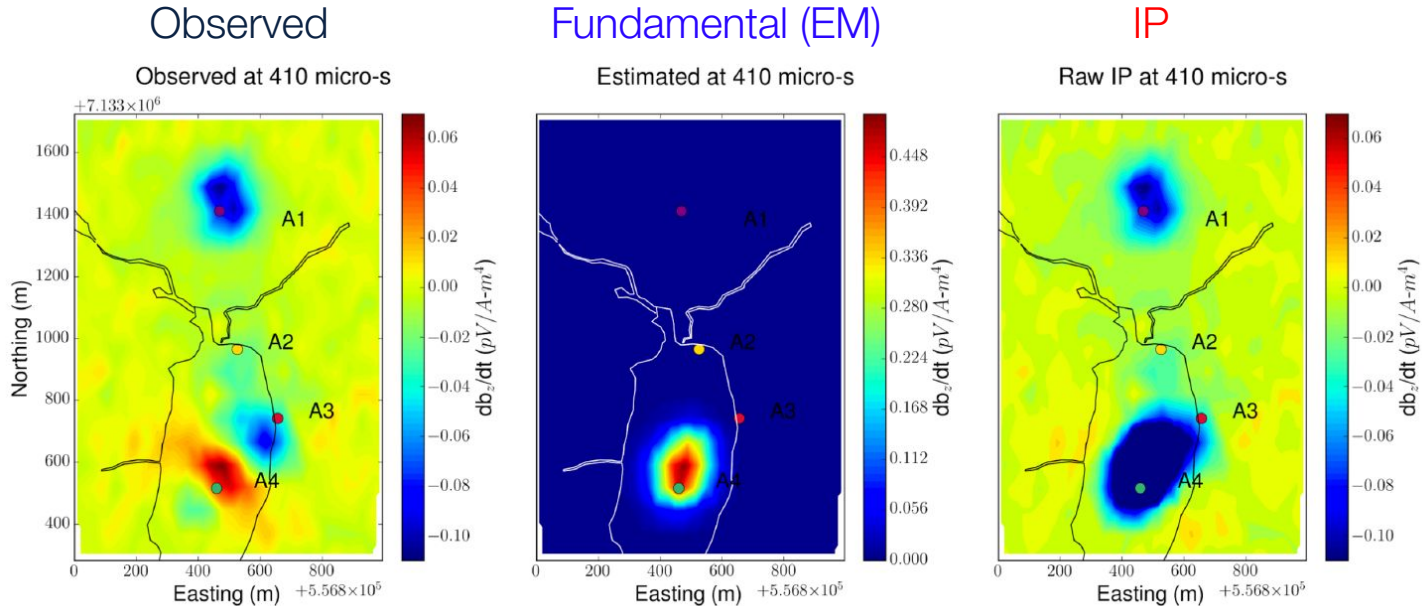
# IP effects in time domain EM data

Negative transients in VTEM presents a challenge → motivates research

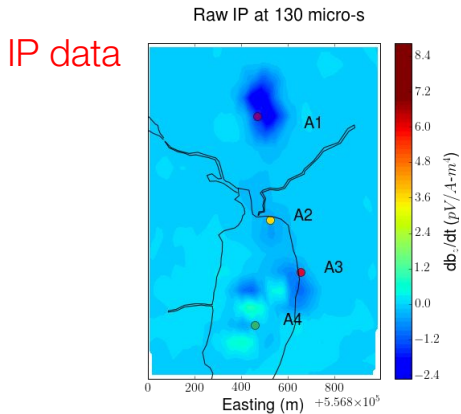
EM-decoupling: **IP** = Observation – Fundamental (EM)



Seogi Kang



# TKC: IP inversion (early time)

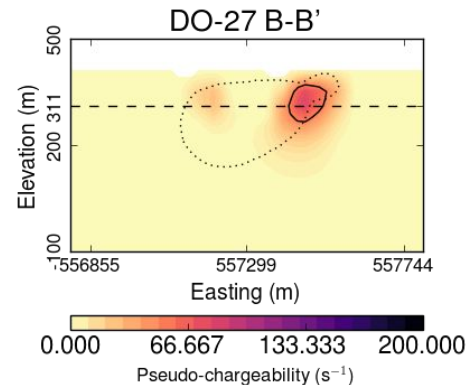
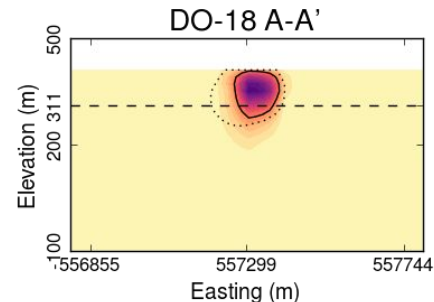
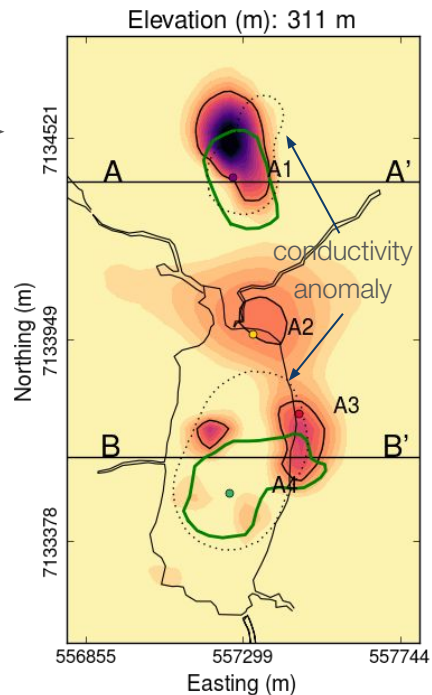


$$d^{IP}(t) = G\tilde{\eta}(t)$$

$G(\sigma_\infty)$ : Sensitivity function  
 $\tilde{\eta}$ : Pseudo-chargeability

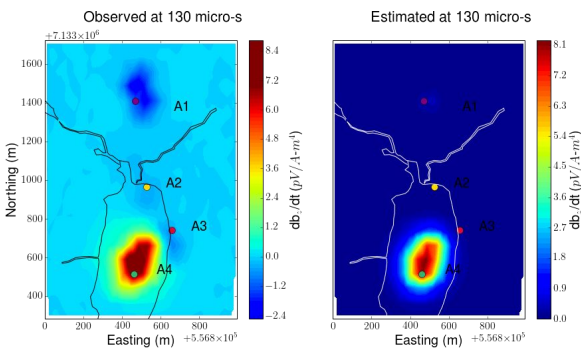
Kang et al. (2016)

## Recovered 3D model



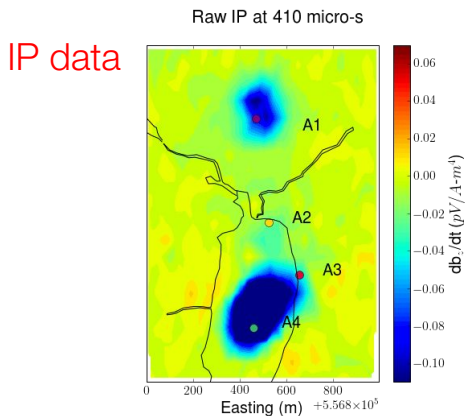
## Observation

## Fundamental



IP = Observation – Fundamental (EM)

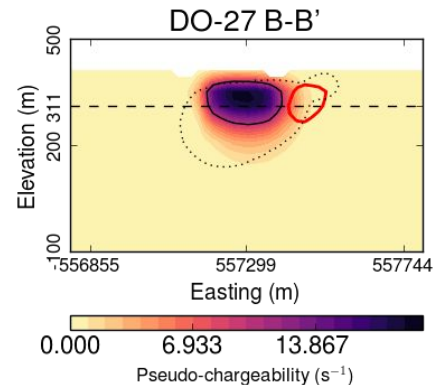
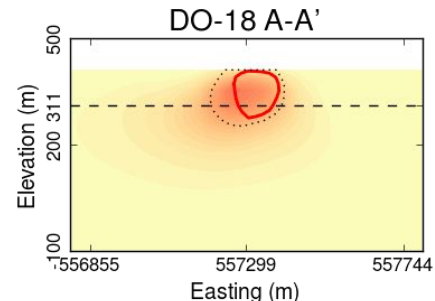
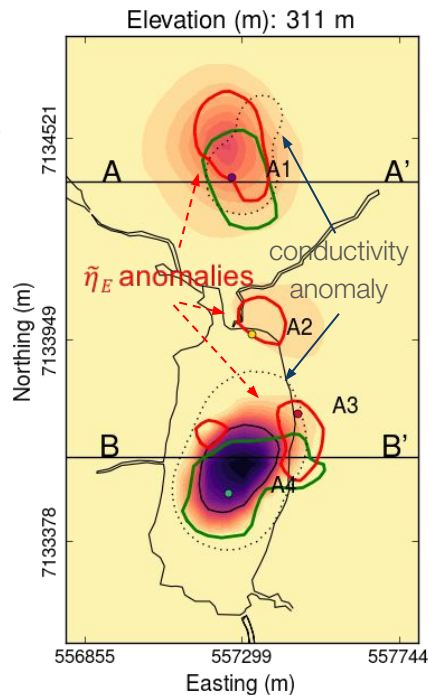
# TKC: IP inversion (late time)



$$d^{IP}(t) = G\tilde{\eta}(t)$$

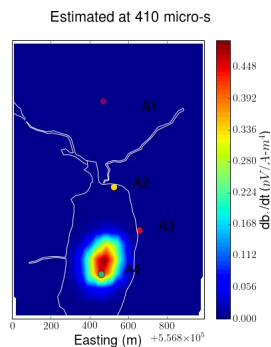
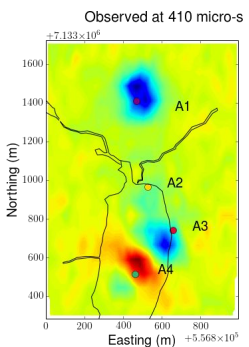
$G(\sigma_\infty)$ : Sensitivity function  
 $\tilde{\eta}$ : Pseudo-chargeability  
 Kang et al. (2016)

## Recovered 3D model



### Observation

### Fundamental



IP = Observation - Fundamental (EM)

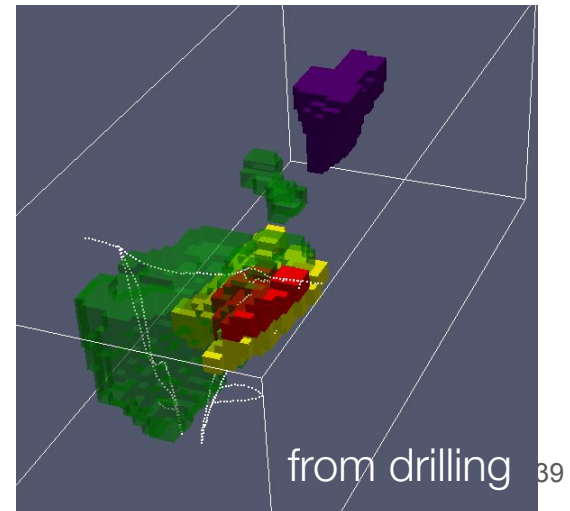
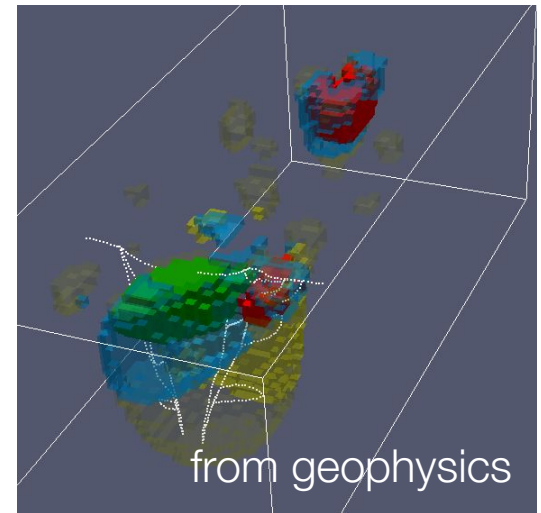
# A quasi-geology model from physical properties

Rock type	Glacial till	Host rock	HK	VK	PK
Density	Moderate	Moderate	Low	Low	Low
Susceptibility	None	None	High	Low-moderate	Low-moderate
Conductivity	Moderate-high	Low	Low-moderate	Moderate-high	Moderate-high
Chargeability	Low	Low	?	?	?

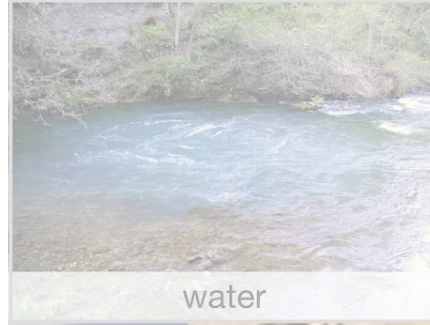
small time  
constant

large time  
constant

- Independently inverted multiple airborne geophysical data sets in 3D, built a representative 3D rock model
- Importance of conductivity, chargeability & related computational tools

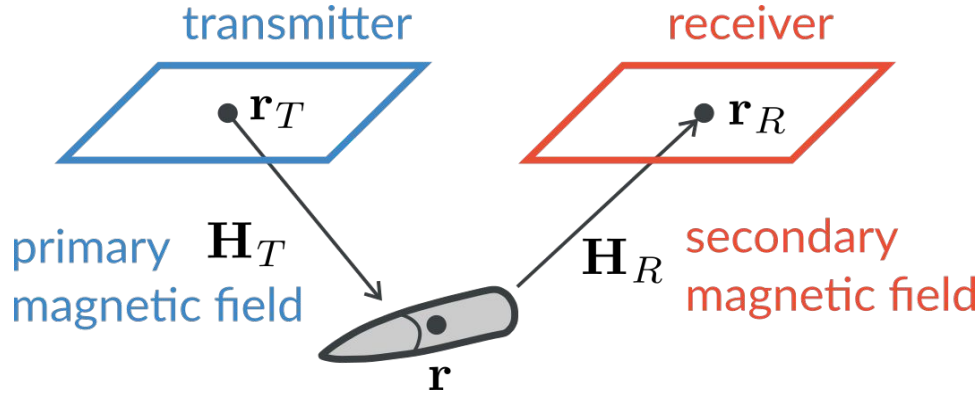


# case studies





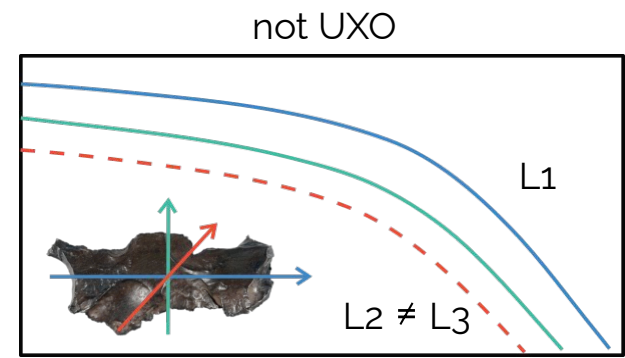
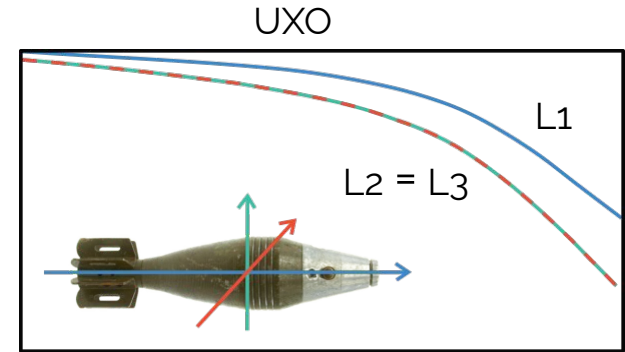
# Time-domain EM response of a UXO



$$d(\mathbf{r}_R, t) = \mathbf{H}_R(\mathbf{r}, \mathbf{r}_R) \cdot \mathbf{P}(t) \cdot \mathbf{H}_T(\mathbf{r}, \mathbf{r}_T)$$

$$\mathbf{P}(t) = \mathbf{A}(\phi, \theta, \psi) \cdot \mathbf{L}(t) \cdot \mathbf{A}^T(\phi, \theta, \psi)$$

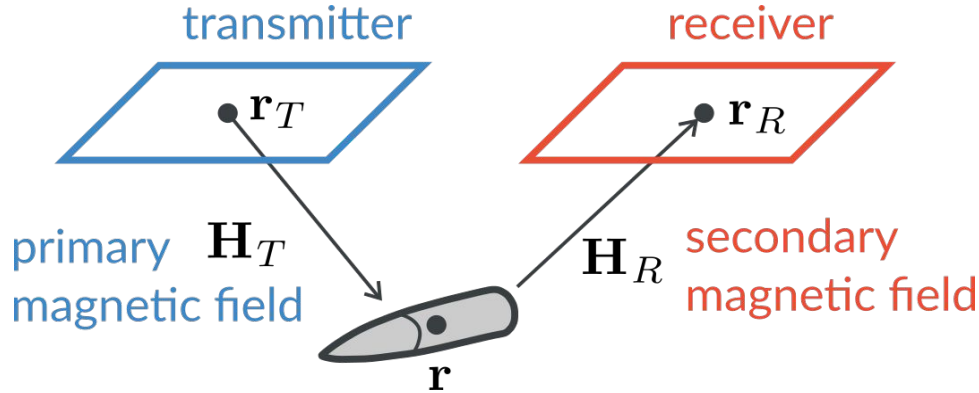
$$\mathbf{L}(t) = \begin{pmatrix} L_1 & & \\ & L_2 & \\ & & L_3 \end{pmatrix}$$



time

→

# Time-domain EM response of a UXO

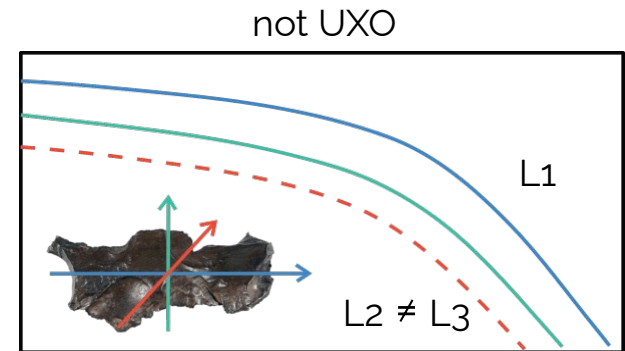
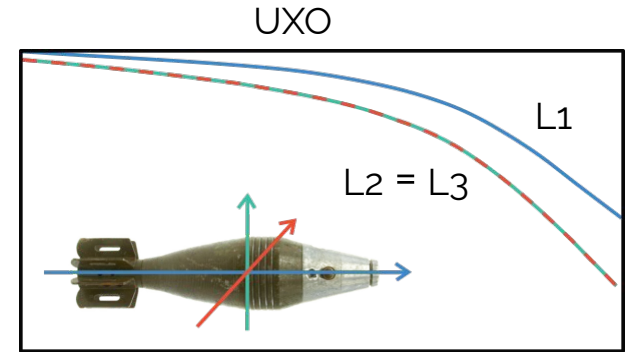


$$d(\mathbf{r}_R, t) = \mathbf{H}_R(\mathbf{r}, \mathbf{r}_R) \cdot \mathbf{P}(t) \cdot \mathbf{H}_T(\mathbf{r}, \mathbf{r}_T)$$

$$\mathbf{P}(t) = \mathbf{A}(\phi, \theta, \psi) \cdot \mathbf{L}(t) \cdot \mathbf{A}^T(\phi, \theta, \psi)$$

$$\mathbf{L}(t) = \begin{pmatrix} L_1 & & \\ & L_2 & \\ & & L_3 \end{pmatrix}$$

traditional approach: use inversion to get these and then classify by comparing  $\mathbf{L}(t)$  with ordnance library



time



# Survey and system



UltraTEMA-4 system:

4 transmitters

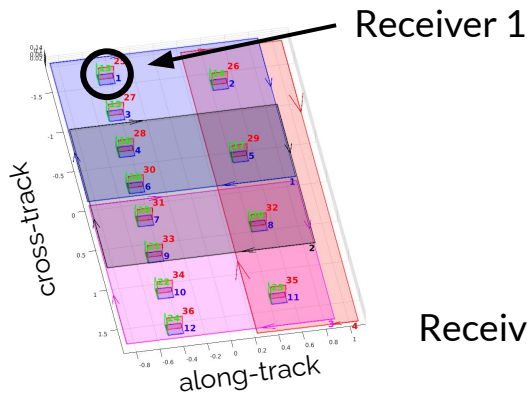
12 receivers (3-component)

27 time channels

Height above seabed: ~1 m

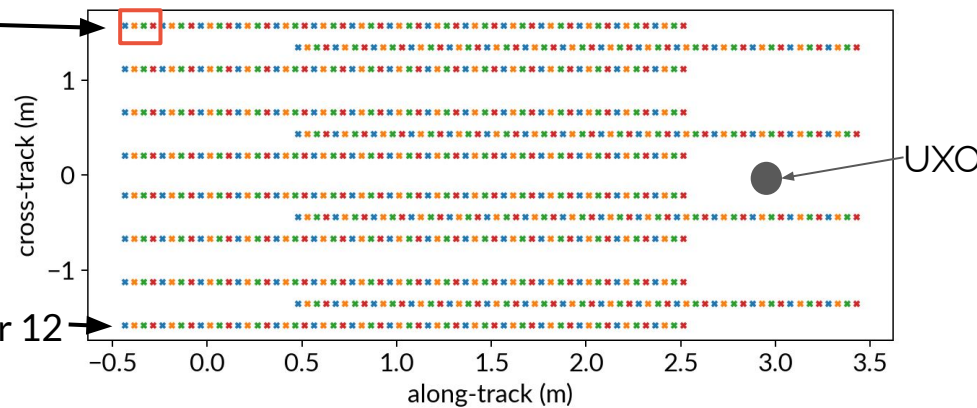
# Data

moving direction



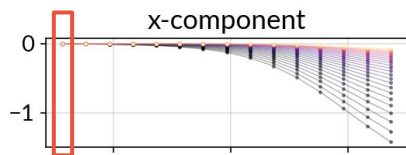
Receiver 1

Receiver 12



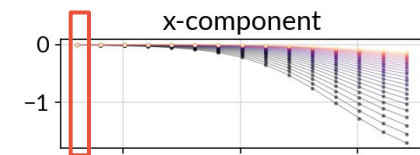
**Transmitter 1**

x-component



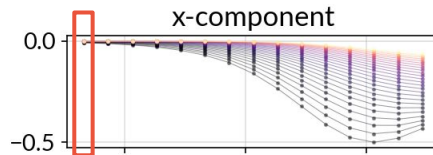
**Transmitter 2**

x-component



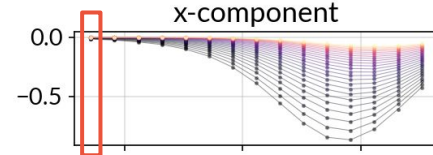
**Transmitter 3**

x-component

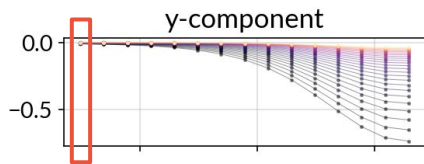


**Transmitter 4**

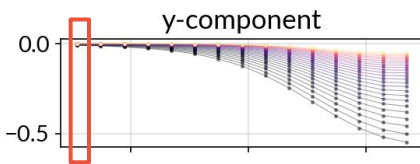
x-component



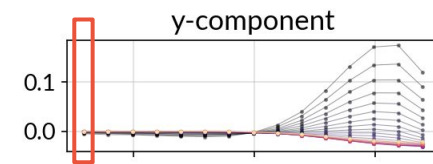
y-component



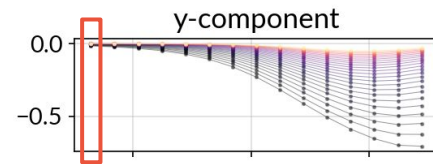
y-component



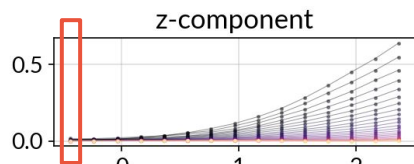
y-component



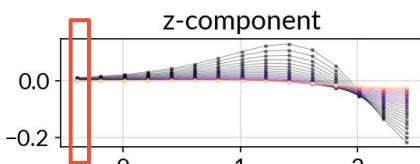
y-component



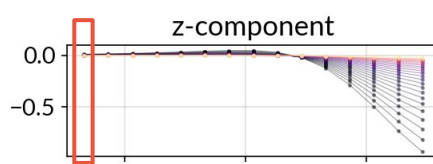
z-component



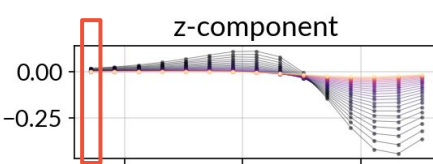
z-component



z-component

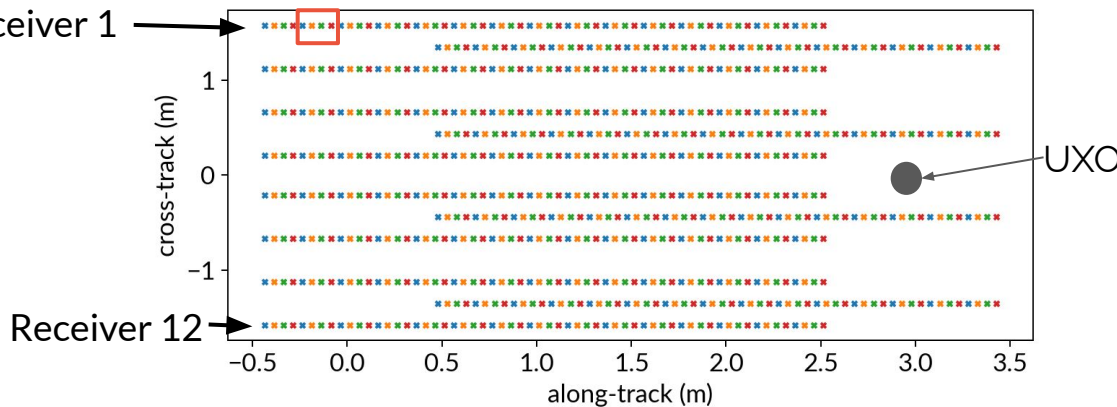
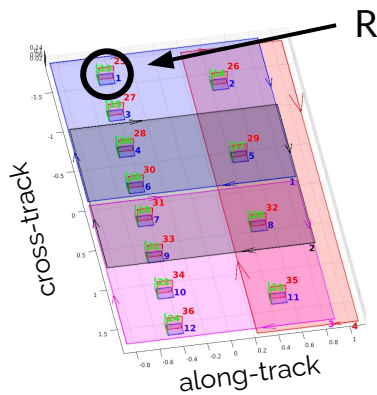


z-component



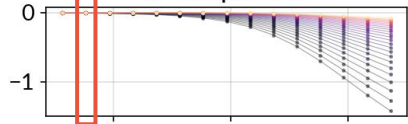
Data

moving direction

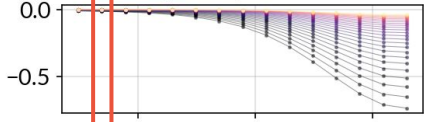


**Transmitter 1**

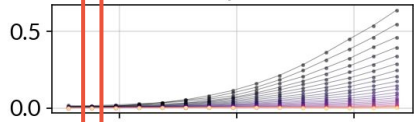
x-component



y-component



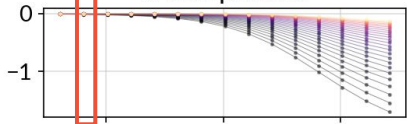
z-component



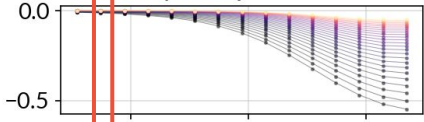
along-track (m)

**Transmitter 2**

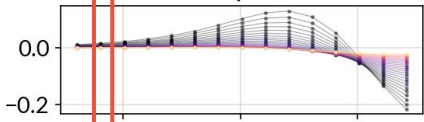
x-component



y-component



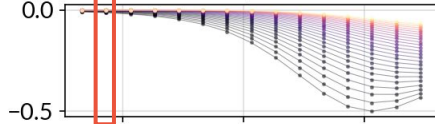
z-component



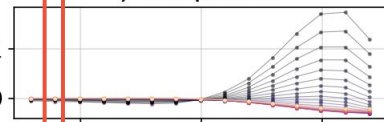
along-track (m)

**Transmitter 3**

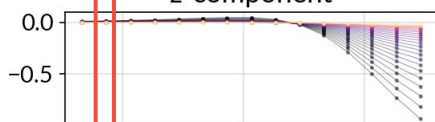
x-component



y-component



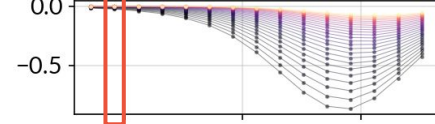
z-component



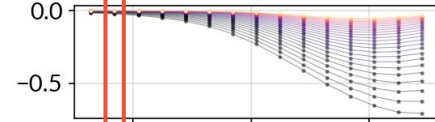
along-track (m)

**Transmitter 4**

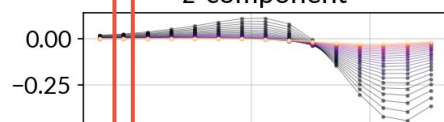
x-component



y-component



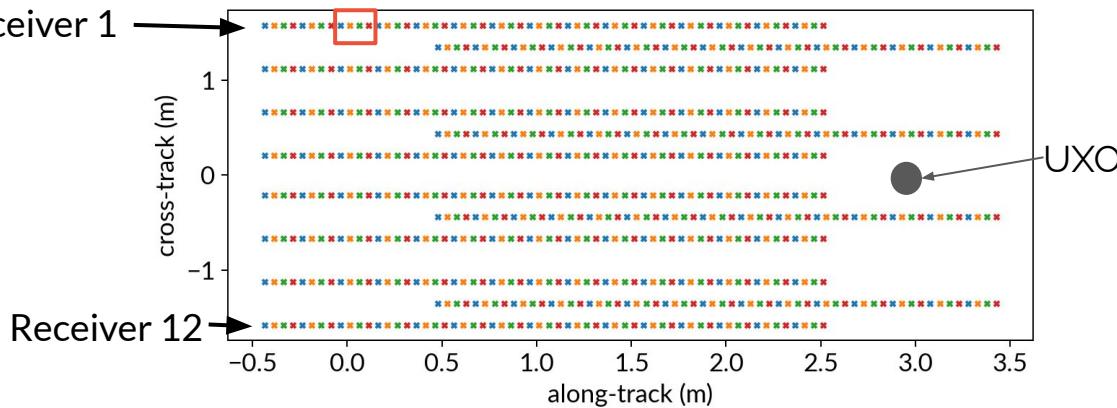
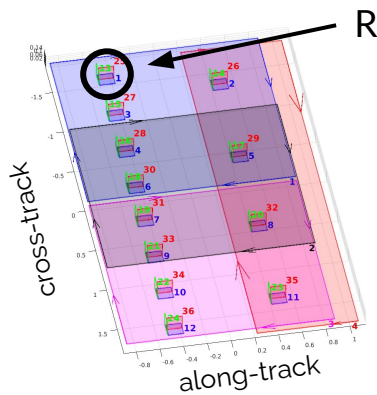
z-component



along-track (m)

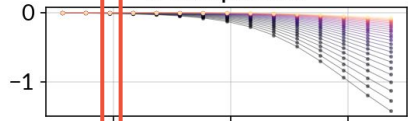
# Data

moving direction

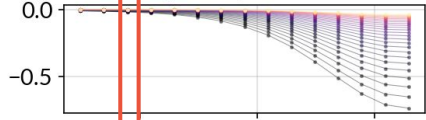


### Transmitter 1

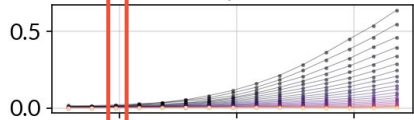
x-component



y-component

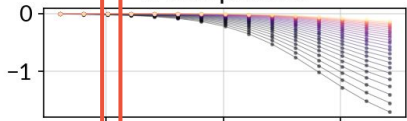


z-component

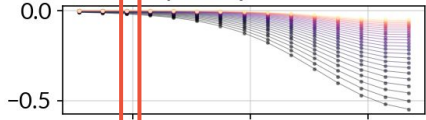


### Transmitter 2

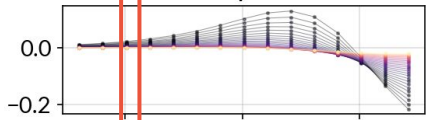
x-component



y-component

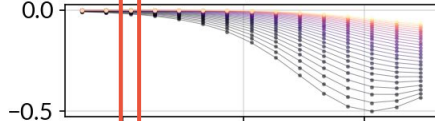


z-component

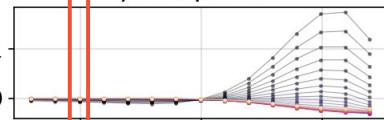


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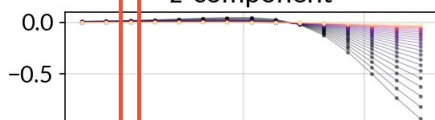
x-component



y-component

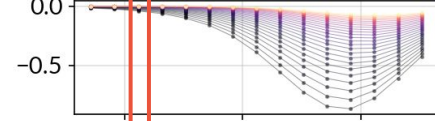


z-component

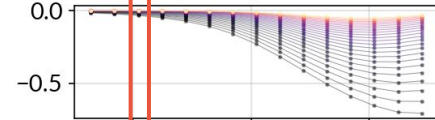


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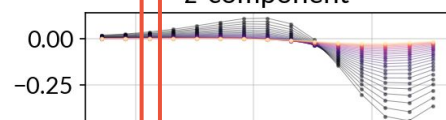
x-component



y-component

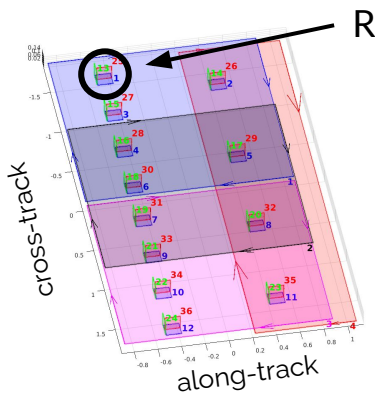


z-component



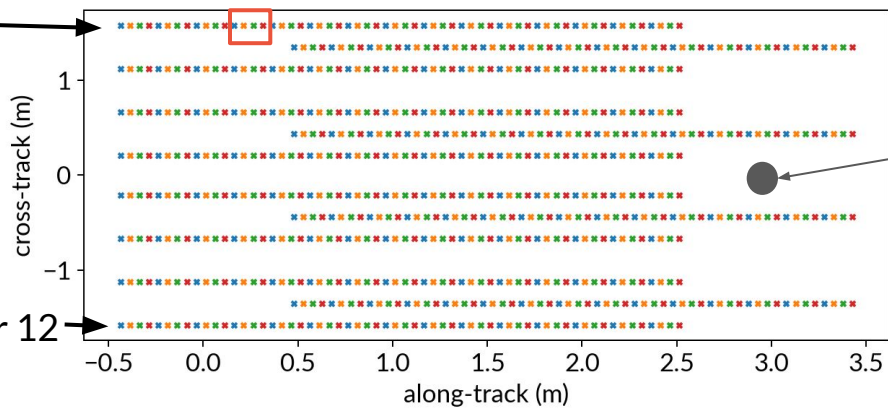
# Data

moving direction

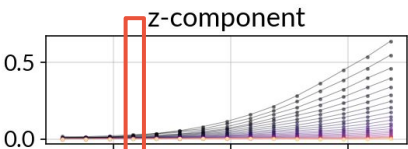
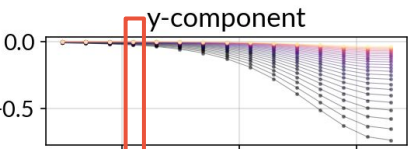
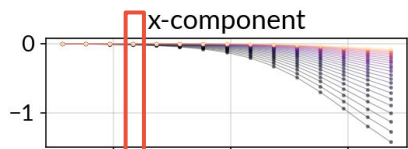


Receiver 1

Receiver 12

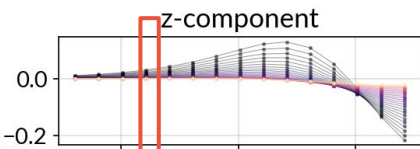
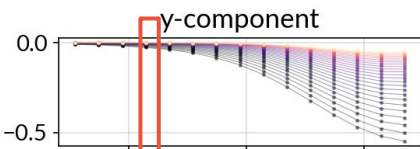
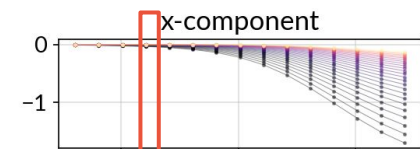


### Transmitter 1



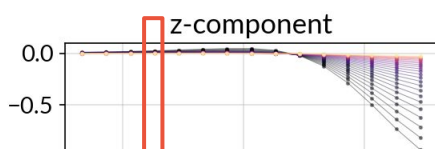
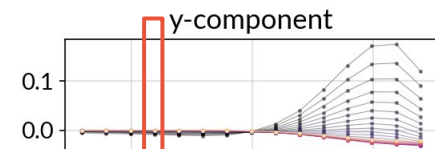
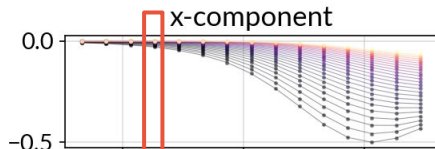
along-track (m)

### Transmitter 2



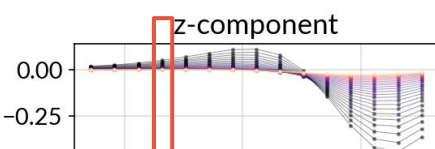
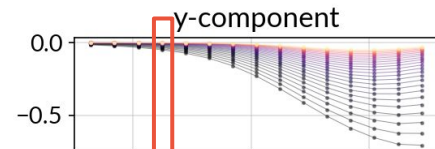
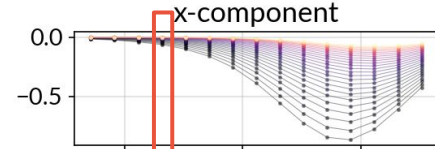
along-track (m)

### Transmitter 3



along-track (m)

### Transmitter 4



along-track (m)

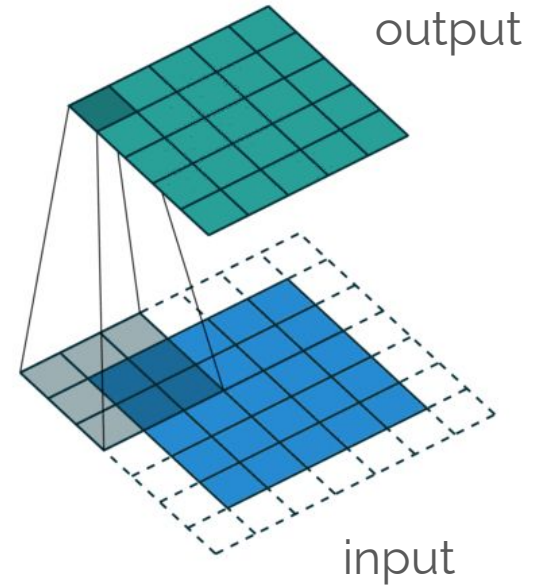
# Can we classify directly from EM data?

## Convolutional neural networks (CNNs)

- Convolutional filters look at spatial / temporal features in the data

## Training EM data for UXO classification:

- Available library of ordnance objects with polarizations
- Fast geophysical simulations





# Convolutional Neural Networks (CNNs)

Supervised classification problem

provided data with labels, construct a function (network) that outputs labels given input data

Input

Features

Neural network

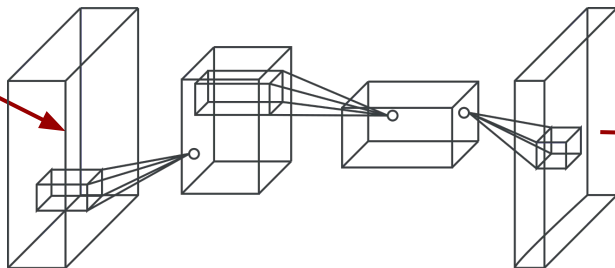
Class probabilities

predicted



$\mathbf{X}$

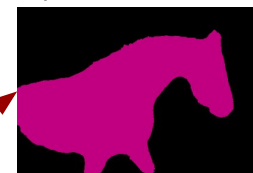
$(n_x \times n_y \times 3)$



$$\mathbf{s} = \mathcal{F}_\theta(\mathbf{X})$$

$p(j|\mathbf{s})$

$\mathbf{S}$



true

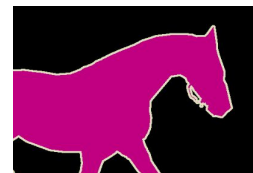
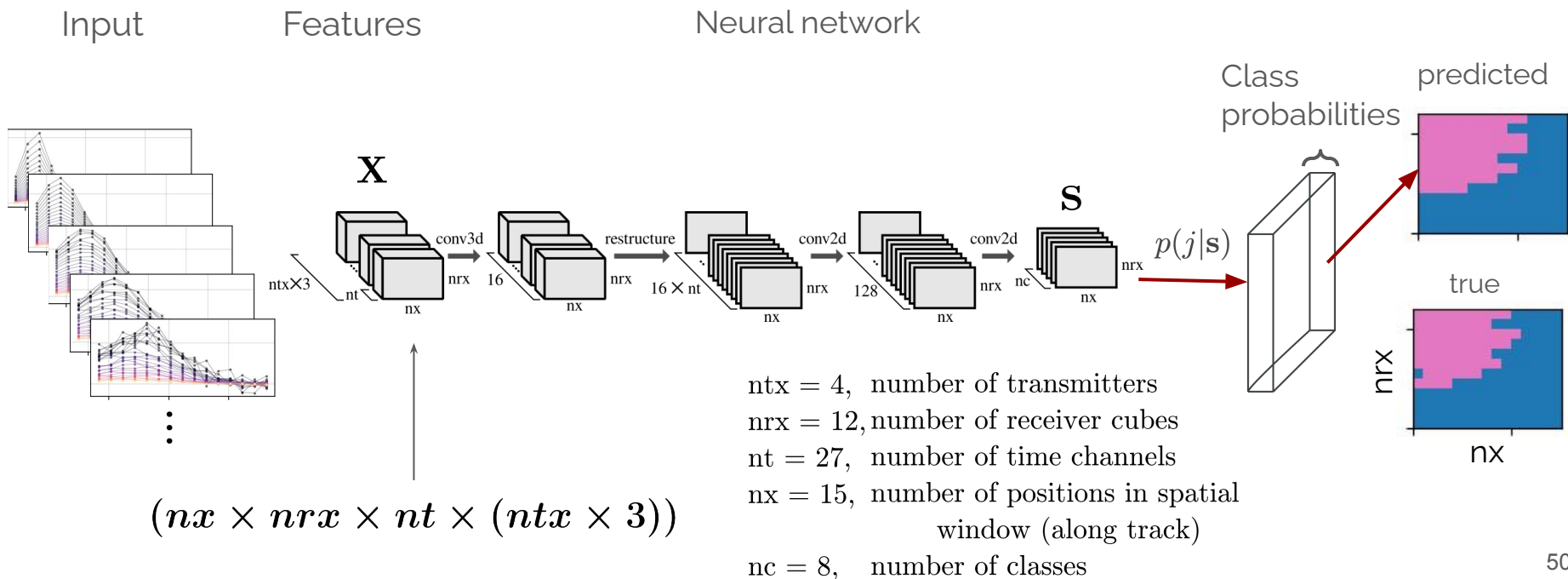


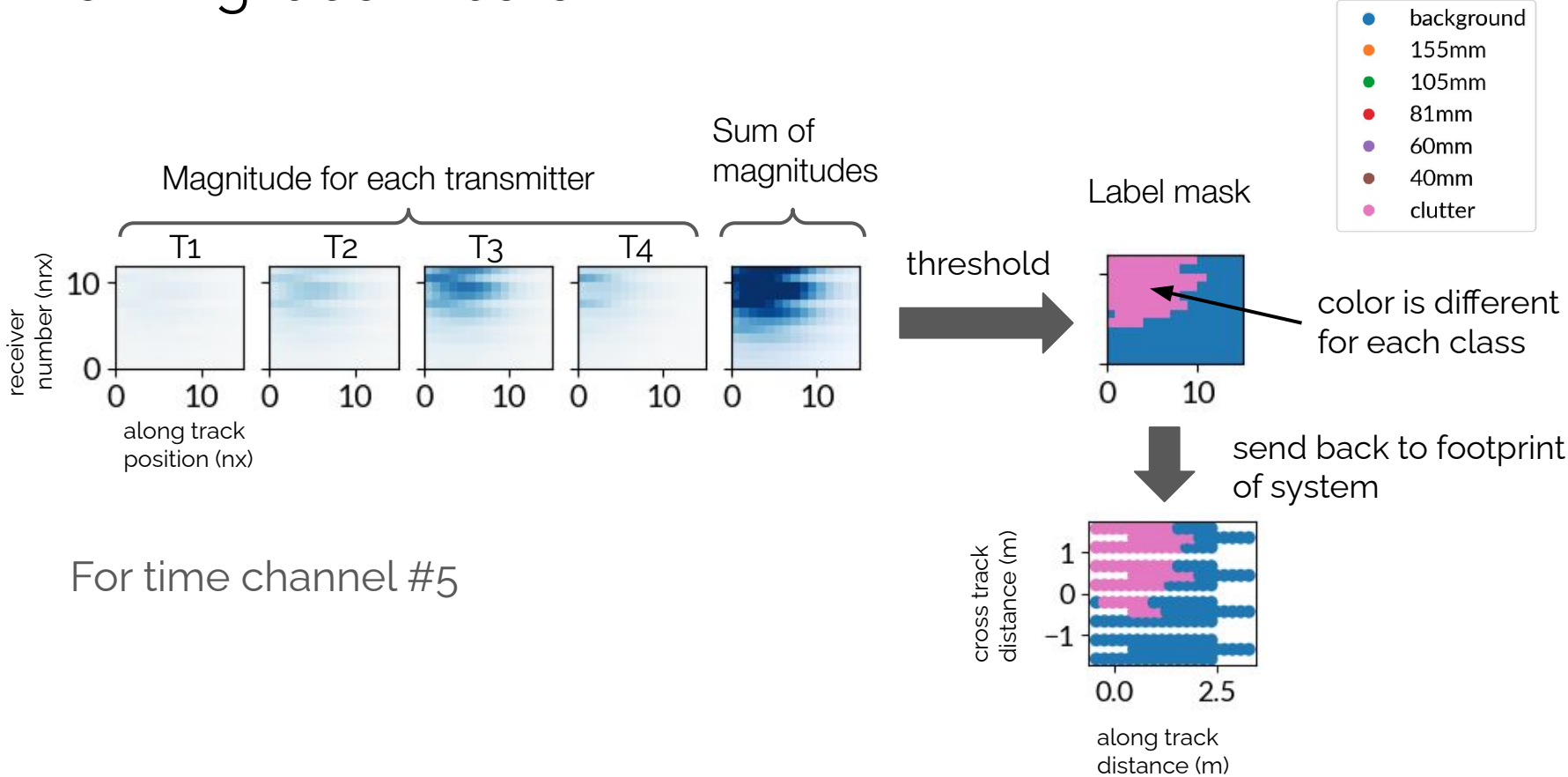
Image segmentation

# Convolutional Neural Networks (CNNs)

How do we translate these things to the UXO classification problem?



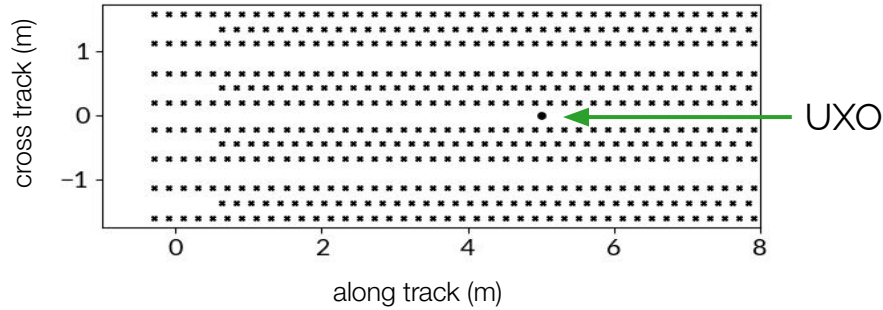
# Defining label masks



For time channel #5

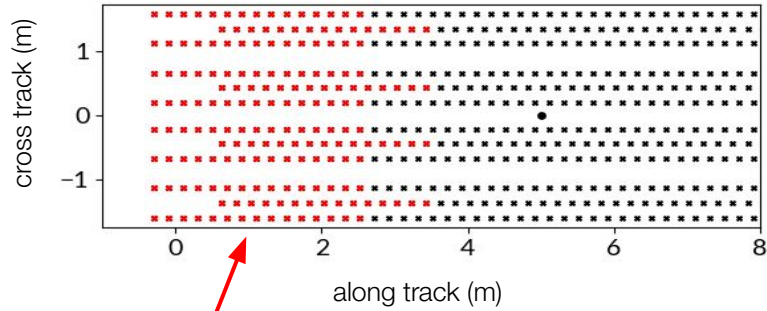
# Application to a line of data

Input features are created by using a sliding window:



# Application to a line of data

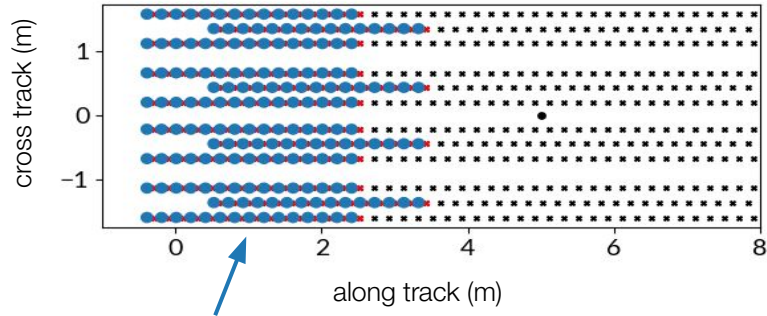
Input features are created by using a sliding window:



sliding window

# Application to a line of data

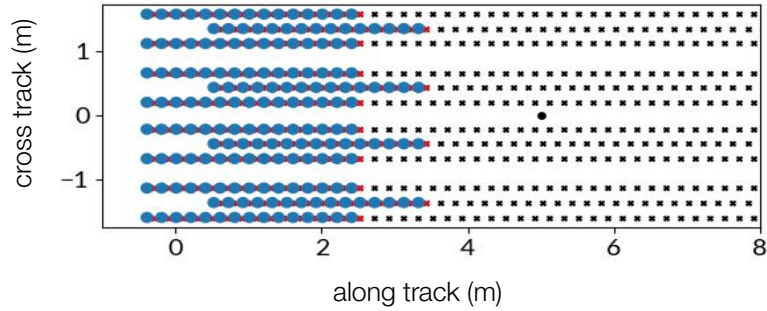
Input features are created by using a sliding window:



Neural network output (class)

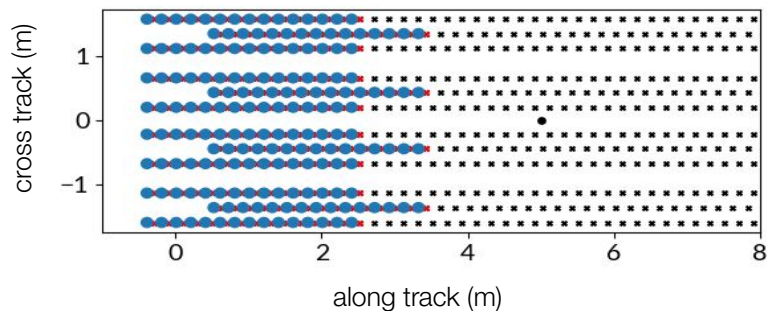
# Application to a line of data

Input features are created by using a sliding window:

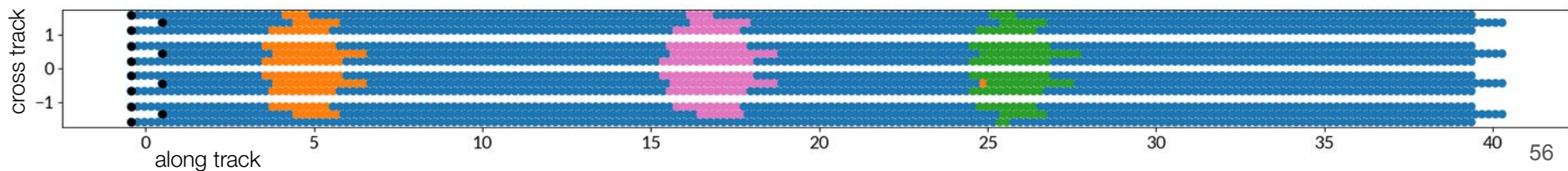


# Application to a line of data

Input features are created by using a sliding window:



Single acquisition line with three objects (classification results)





# Training dataset: dipole forward model

7 classes:

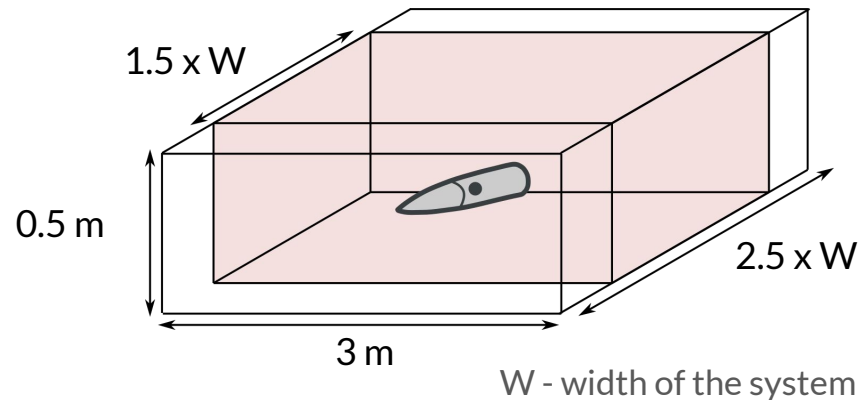
- background
- 155 mm
- 105 mm
- 81 mm
- 60 mm
- 40 mm
- clutter

# of realizations:

- Training (multi-class): 400,000
- Validation: 10,000

Randomly assign:

- Target class
- Location  $(x, y, z)$
- Orientation  $(\phi, \theta, \psi)$
- Noise level: approximate from background areas in the field data



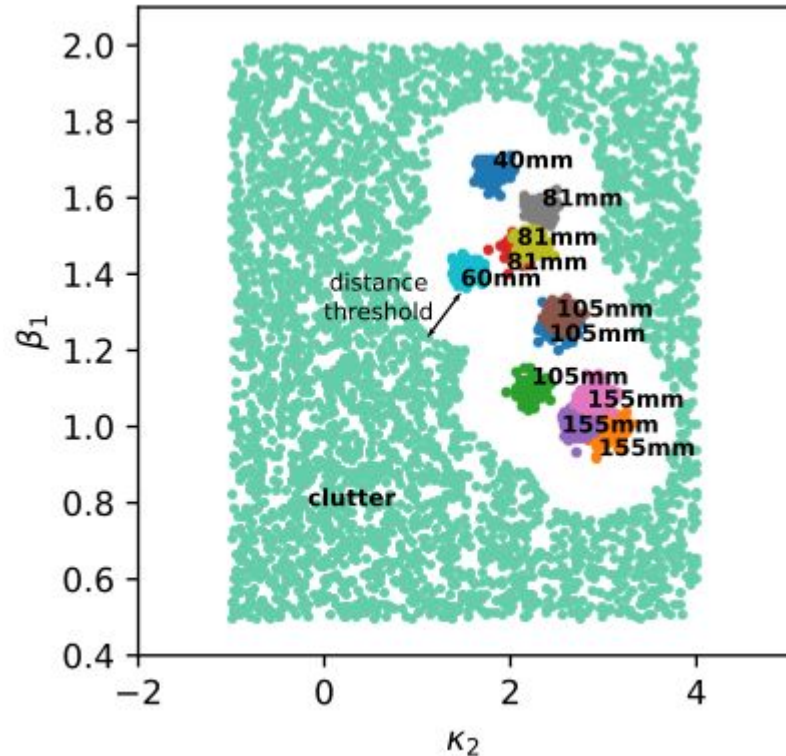
# Clutter design

Physics-based parameterization of EM decay:

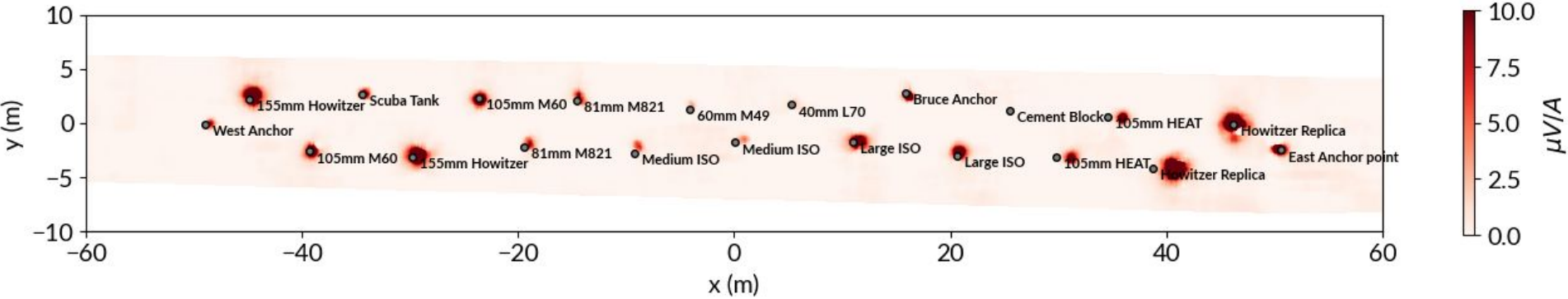
$$L(t) = kt^{-\beta} \exp(-t/\gamma)$$

9 parameters in total:

1. Estimate values for UXOs in ordnance library
2. Define a distance threshold
3. Fill the remaining space with clutter objects

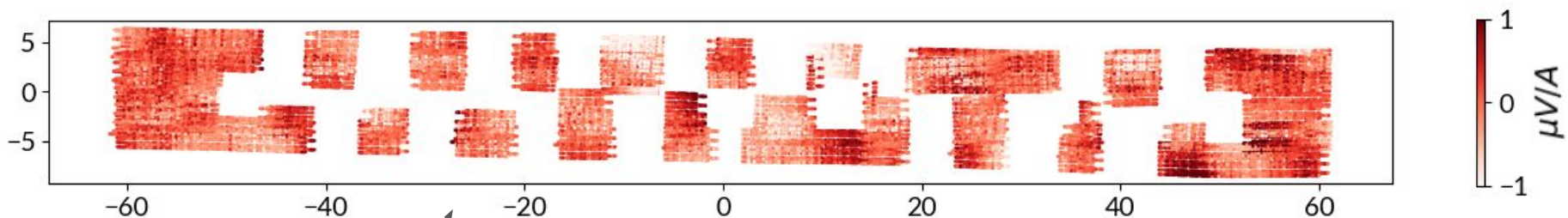
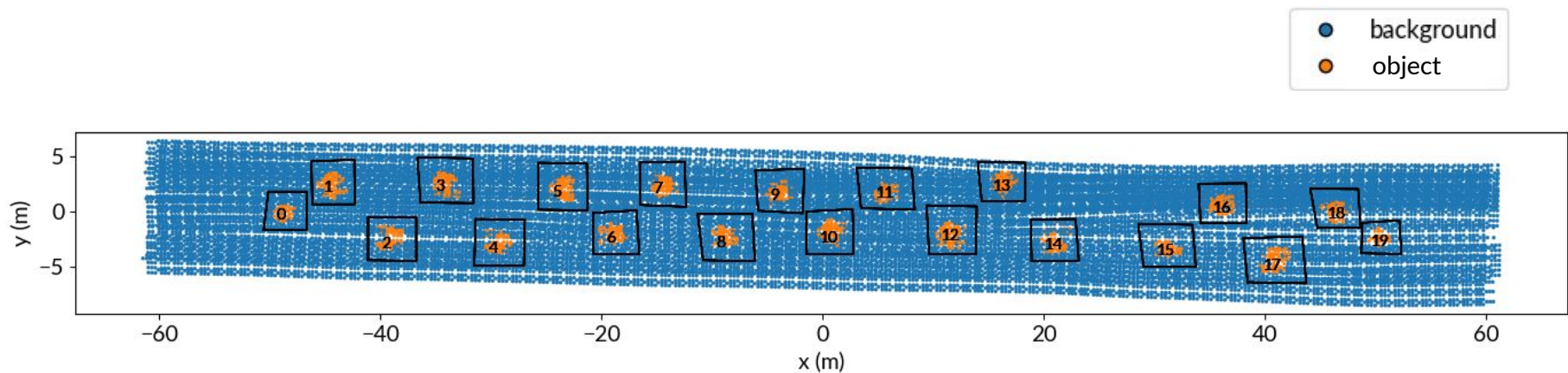


# Field data - Sequim Bay test site (2022)



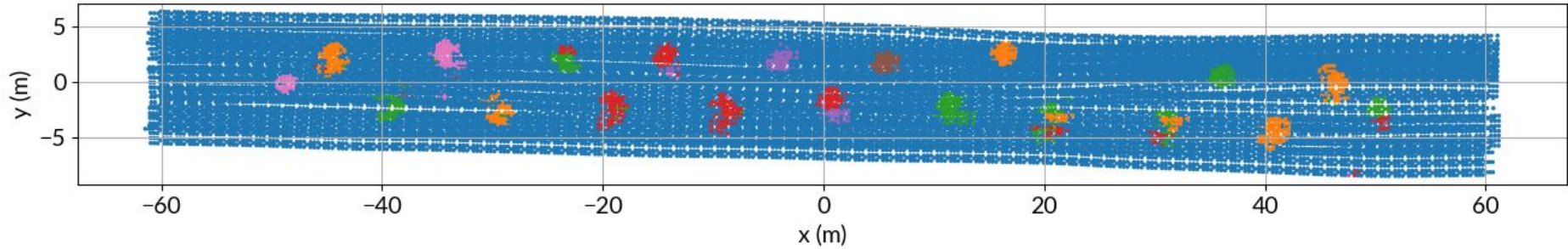
- 7 acquisition lines
- Current workflow requires seawater response removed
- Some ISOs present, we used only UXO objects to train (e.g. medium ISO ~ 81mm)

# Get correlated noise using a binary classifier

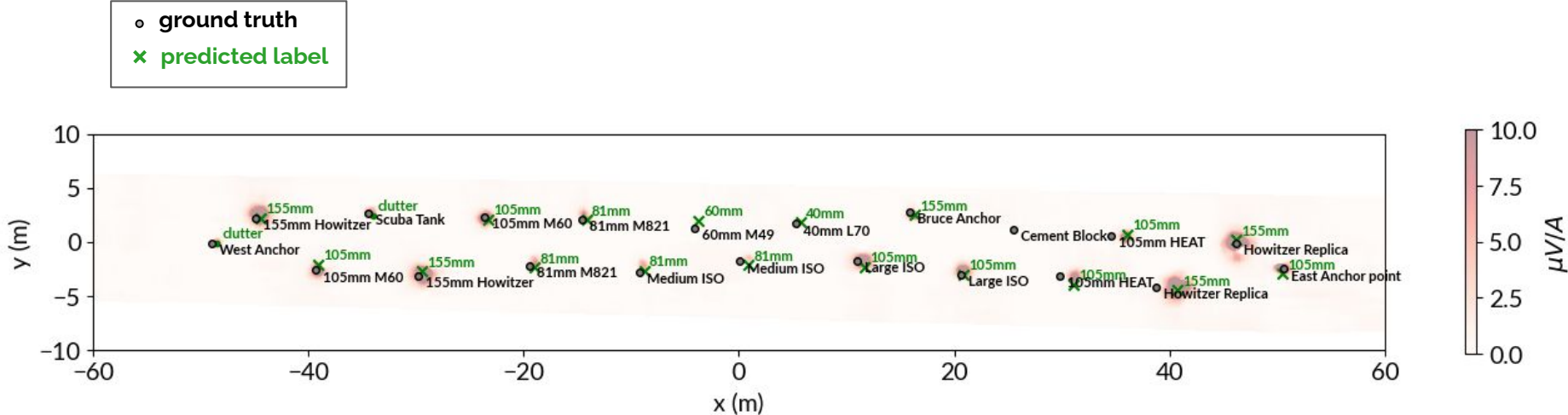


get spatially correlated noise from this subset of field data

# Classification map (output of CNN)



# Predicted labels vs truth labels - field data

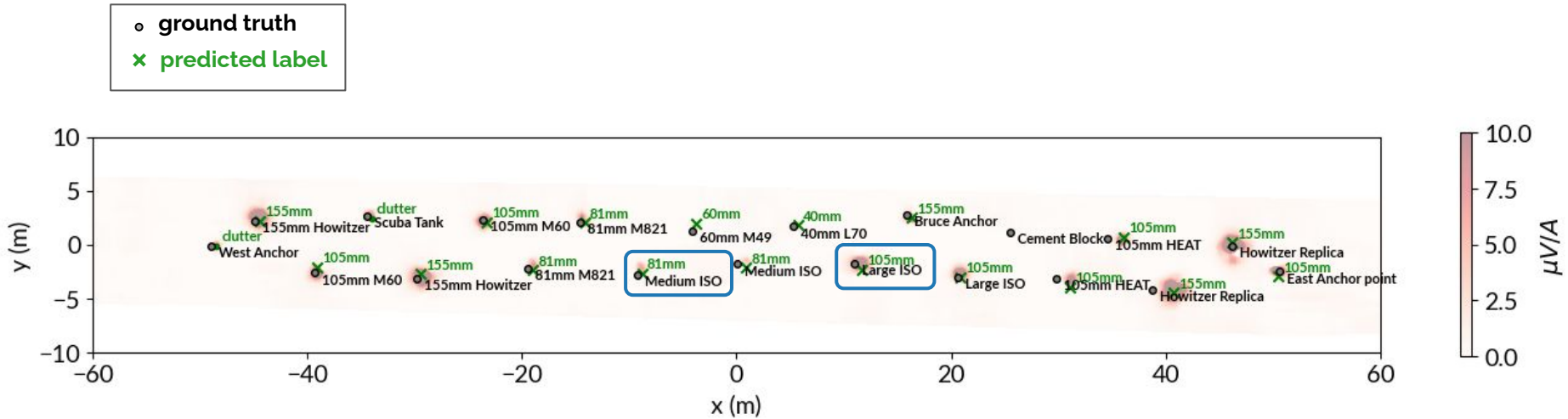








# Predicted labels vs truth labels - field data



- Discriminated clutter
- Did not miss any UXO
- Classified to closest object in training dataset

# UXO classification

Key points:

- image-segmentation architecture
- clutter design and correlated noise are important

Some limitations:

- not trained to handle multiple objects in the same window
- objects used to generate synthetic data should be close to the objects on the field

Future work:

- explore multi-target scenario (maybe instance segmentation)
- combining with traditional approach

# important problems



Electrical conductivity can be a diagnostic physical property in many settings

Electromagnetic methods can be useful across a wide range of scales

Numerical tools for simulation, inversion, machine learning enable understanding of physical responses, invaluable for interpretation of data

# Thank you!



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